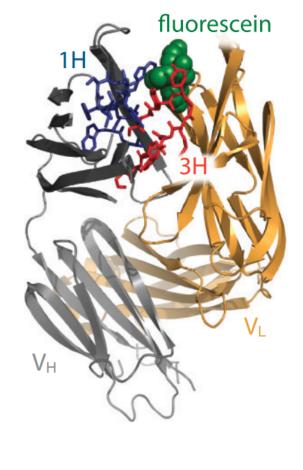


Motivation

- Active learning, experimental design and protein engineering are instances of combinatorial optimization.
- These problems are usually NP-hard.
- Greedy could be intractable and/or highly suboptimal.



Our Approach

- ML framework that learns a greedy heuristic based on the **submodular-norm loss**.
- The learned objective is permutation-invariant and approximately submodular with **strong** approximation guarantees.
- The model is easily integrated with ML pipelines.

Submodular Surrogates

Given: ground set \mathcal{V} ; value function $u: 2^{\mathcal{V}} \to \mathbb{R}$; budget k.

Goal: Policy $\pi: 2^{\mathcal{V}} \to \mathcal{V}$ that maximizes $u(S_{\pi,k})$ by iteratively adding to the set:

 $S_{\pi,i} = S_{\pi,i-1} \cup \{\pi(S_{\pi,i-1})\}.$

Approach: Design a surragate objective function $f: 2^{\mathcal{V}} \to \mathbb{R}$ which is

- Monotone: $\forall A \subseteq \mathcal{V} \text{ and } e \in \mathcal{V} \setminus A$, $f(A) \le f(A \cup \{e\}).$
- Submodular: $\forall A \subseteq B \subseteq \mathcal{V} \text{ and } e \in \mathcal{V} \setminus B$, $f(A \cup \{e\}) - f(A) \ge f(B \cup \{e\}) - f(B).$ • Approximately equal to oracle *u*.
- If we had a "good" submodular surrogate f:
- Let $g(A, e) = f(A \cup \{e\}) f(A)$ for $A \subset \mathcal{V}$ and $e \in \mathcal{V}$.
- $g(A, e) \approx g^{\exp}(A, e) = u(A \cup \{e\}) u(A)$
- $\pi(S) = \arg \max_{e \in \mathcal{V}} g(S, e)$ is **near-optimal**.

Problem: Hand-engineering f is hard; evaluating $q^{\rm exp}$ is expensive.

Learning to Make Decisions via Submodular Regularization Ayya Alieva³, Aiden Aceves¹, Jialin Song¹, Stephen Mayo¹, Yisong Yue¹, Yuxin Chen² ¹Caltech, ²University of Chicago, ³Stanford University

Learning with Submodular **Regularization** (LeaSuRe)

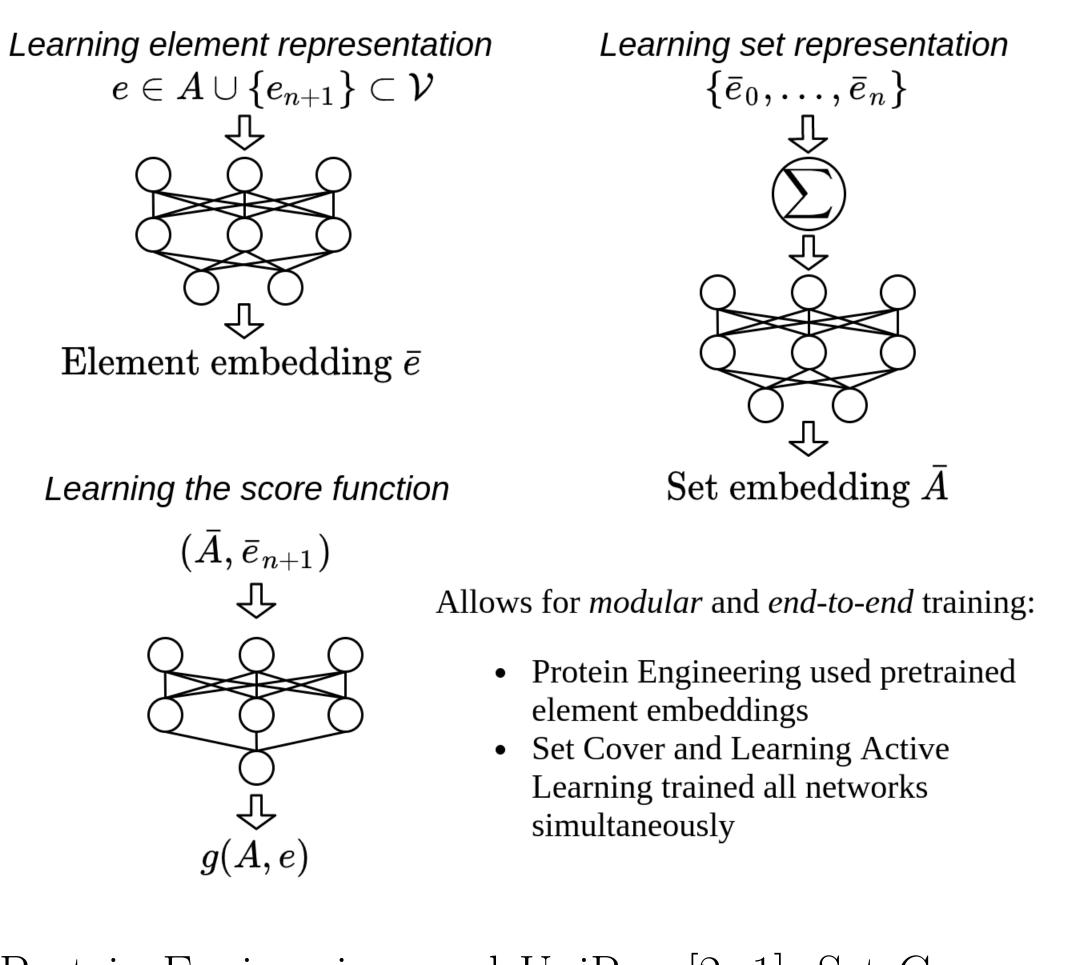
We train NN $g: 2^{\mathcal{V}} \times \mathcal{V} \to \mathbb{R}$ to approximate g^{\exp} :

- DAgger [5] collects **real labelled** dataset $D_{real} = \{(\langle A, x \rangle, g^{\exp}(A, x))\}.$
- For $\langle A, x \rangle \in D_{real}$ we generate random *superset* A' and form an **unlabelled** synthetic dataset $D_{synth} = \{ (\langle A, x \rangle, \langle A', x \rangle) | A \preceq A', \langle A, x \rangle \in D_{real} \}$
- We update g using **submodular-norm** loss:

$$\begin{split} \mathrm{Loss}(g, g^{\mathrm{exp}}) &= \sum_{\substack{\langle A, x \rangle \in D_{real}}} (g^{\mathrm{exp}}(A, x) - g(A, x))^2 \\ &+ \lambda \sum_{\substack{\langle \langle A, x \rangle, \langle A', x \rangle) \in D_{synth}}} \sigma([g(A', x) - g(A, x)]) \\ &+ \gamma \sum_{\substack{\langle A', x \rangle \in D_{synth}}} \mathrm{ReLu}(-g(A', x)), \end{split}$$

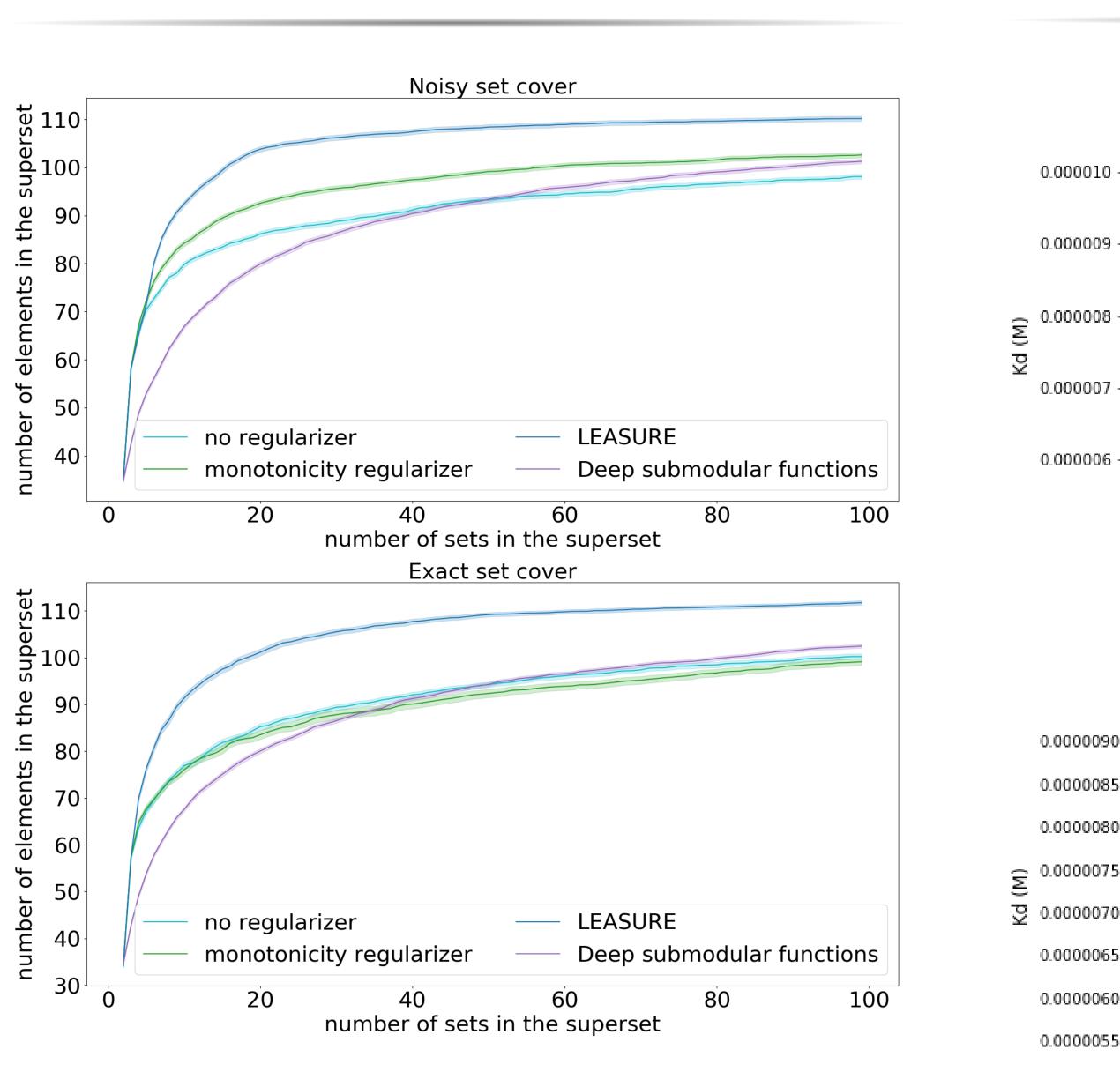
LEASURE encourages g to model the gain of a **monotone**, **submodular** function approximating the oracle u.

Architecture

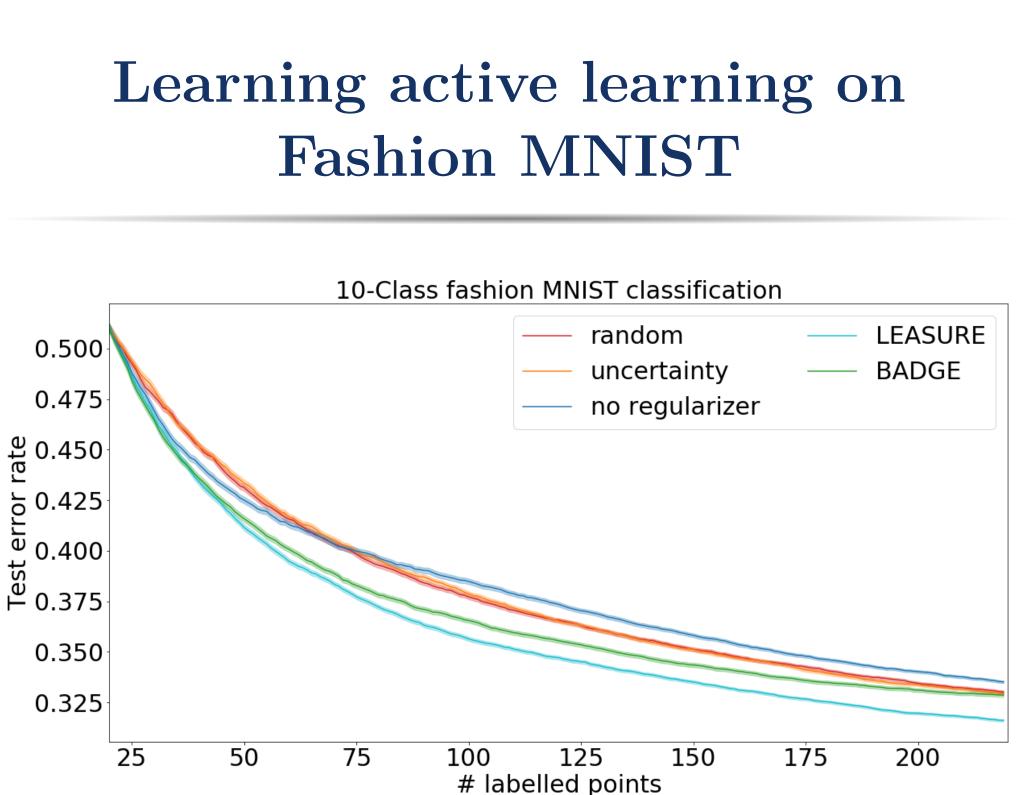


Protein Engineering used UniRep [2, 1]; Set Cover and Learning Active Learning used a two layer DNN.





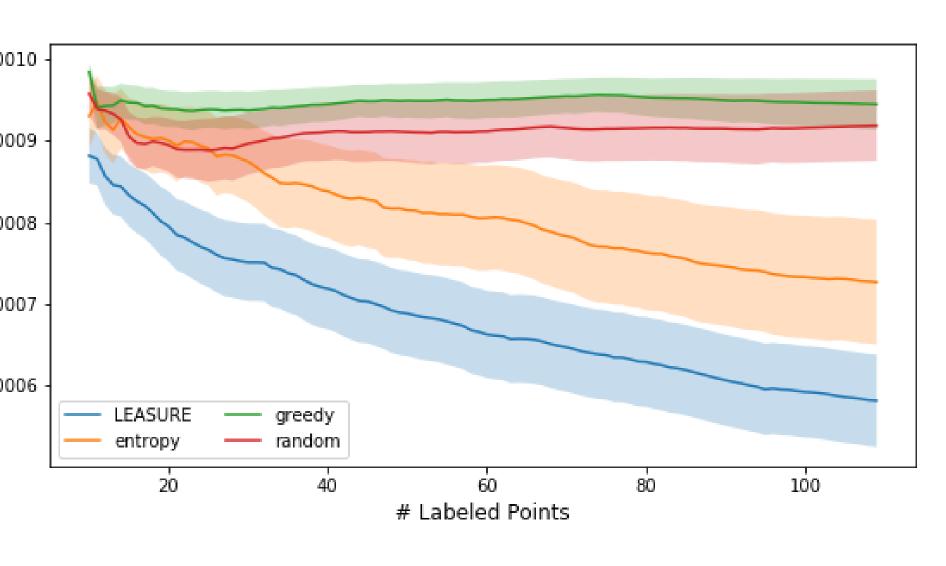
Baselines: "no regularizer" - MSE loss; "monotonicity regularizer" - MSE + ReLu loss; Deep Submodular Functions [4].



Baselines: "random" - random sampling; "uncertainty" - uncertainty sampling; "no regularizer" -DAgger + MSE loss; BADGE [3].

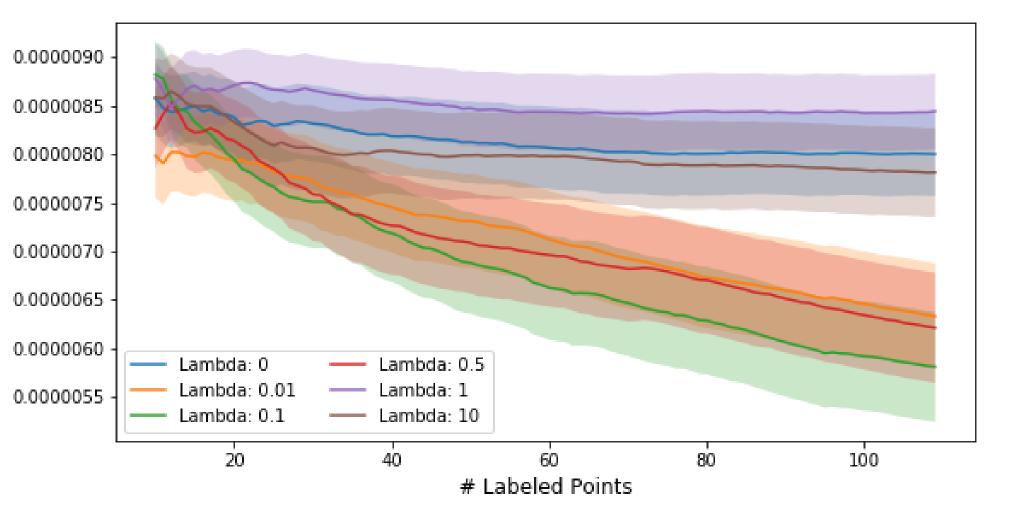
[5] Ross, S., Gordon, G., and Bagnell, D. (2011).

Protein Engineering



Comparison to baseline methods

Effect of scaling parameter λ for LEASURE



Given: A large set of unlabelled proteins.

Goal: Determine a subset of high-potency (low K_D) proteins.

Problem: The protein set is too large to test the potency of all elements.

Baselines: "random" - random sampling; "greedy" - hand-engineered surrogate g; "entropy" - a version of uncertainty sampling.

References

[1] Aceves, A. (2021). Our code. https://gitlab.com/ ajaceves/alilpe.

[2] Alley, E. C., Khimulya, G., Biswas, S., AlQuraishi, M., and Church, G. M. (2019).

[3] Ash, J. T., Zhang, C., Krishnamurthy, A., Langford, J., and Agarwal, A. (2020).

[4] Dolhansky, B. W. and Bilmes, J. A. (2016).