Contextual Linear Bandit Problem & Applications

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Contents

- Recap of last lecture
 - Multi-armed Bandit Problem / UCB1 Algorithm
- Application to News Article Recommendation
- Contextual Linear Bandit Problem
- LinUCB Algorithm
- Disjoint Model & General Model
- Derivation of LinUCB
- News Article Recommendation Revisited
- Conclusion

Last Lecture: Multi-armed Bandit Problem

- K actions (feature-free)
- Each action has an average reward (unknown): μ_k
- For t=1,...,T (unknown)
 - Choose an action a_t from {1, ..., K} actions
 - Observe a random reward y_t where y_t is bounded [0,1]
 - $E[y_t] = \mu_{a,t}$: Expected reward of action a_t
- Minimizing Regret: $R = \sum_{t=1}^{T} [\mu^* \mu_{a,t}]$

Q. How to choose an action to minimize regret?

Last Lecture: UCB1 Algorithm

 At each iteration, choose the action with highest Upper Confidence Bound (UCB)

$$a_{t+1} = \arg\max_{a} \hat{\mu}_{a,t} + \sqrt{\frac{2\ln t}{t_a}}$$
 Exploitation Term Exploration Term

Regret Bound: with high probability, sublinear w.r.t T

$$R(T) = O\left(\frac{K}{\Delta} \ln T\right)$$
 Time Horizon
 Gap between best & 2nd best
 $\Delta = \mu_1 - \mu_2$

Application of Multi-armed Bandit Problem?

News Article Recommendation

- Various algorithms for personalized recommendation
 - Collaborative filtering, Content-based filtering, Hybrid approaches
- But...
 - Web-based contents undergo frequent changes
 - Some users have no previous data to learn from (cold-start problem)
- Exploration vs. Exploitation
 - Need to gather more information about users with more trials
 - Optimize the article selection with past user experience
 - → Use multi-armed bandit setting

Users u₁ with age YOUNG and u₂ with age OLD



 u_1



 u_{2}

Retirement planning wishes vs. reality

The Player Wizarding World of Harry Potter ride may conjure a new path for theme park rides

Elon Musk: 198,000 Tesla Model 3 Orders Received in 24 Hours

Not tired yet: Warriors top Spurs for 72nd win, set up date with history

User u₁ with age YOUNG



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 U_1

- O.2 Retirement planning wishes vs. reality
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O.2 Retirement planning wishes vs. reality

The Player Wizarding World of Harry Potter 0.4 ride may conjure a new path for theme park rides

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User u₂ with age OLD



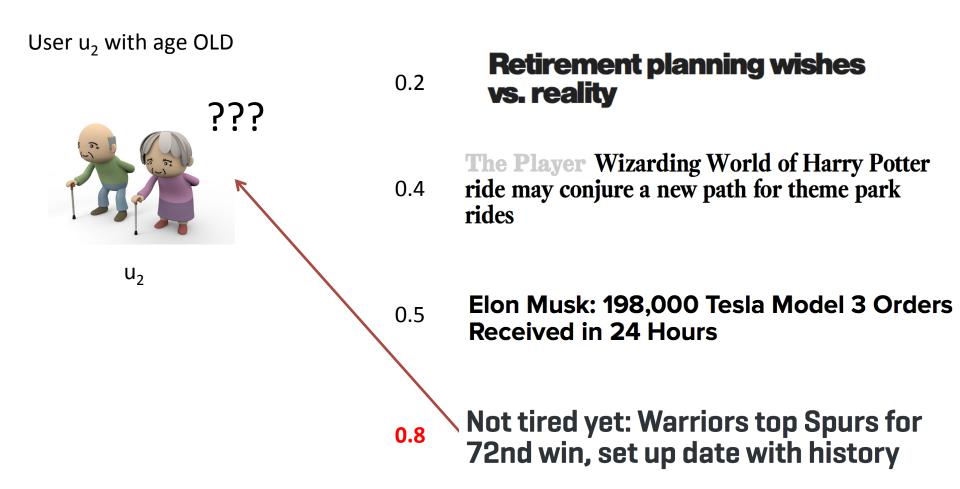
 u_2

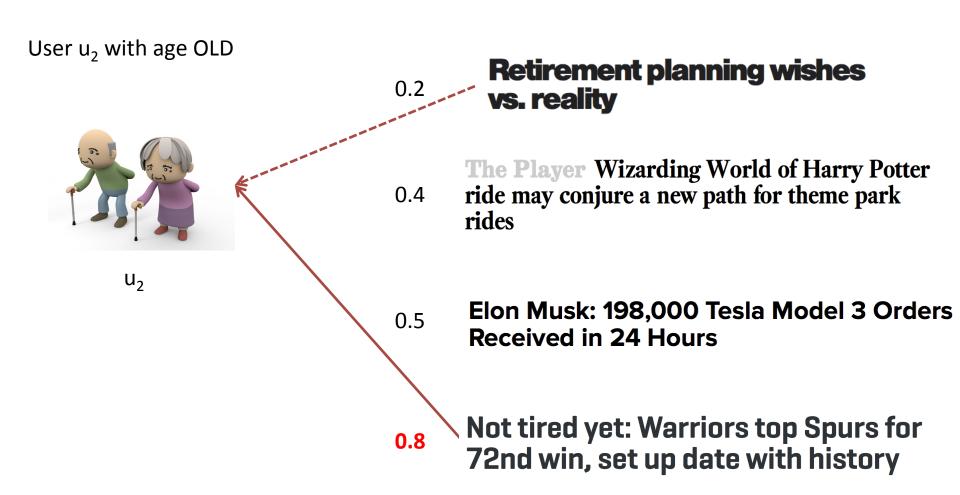
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User u₂ with age OLD Retirement planning wishes 0.2 vs. reality The Player Wizarding World of Harry Potter ride may conjure a new path for theme park 0.4 rides u_2 Elon Musk: 198,000 Tesla Model 3 Orders 0.5 Received in 24 Hours

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Contextual-Bandit Problem

- For t=1,...,T (unknown)
 - User u_t, set A_t of actions (a)
 - Feature vector (context) $\mathbf{x}_{t,a}$: summarizes both user \mathbf{u}_t and action a
 - Based on previous results, choose a_t from A_t
 - Receive payoff r_{t,a_t}
 - Improve selection strategy with new observation set $(x_{t,a_t}, a_t, r_{t,a_t})$

• Minimizing Regret:
$$R(T) = \mathbf{E} \left[\sum_{t=1}^{T} \left(r_{t,a_t^*} - r_{t,a_t} \right) \right]$$

Action with maximum expected payoff at time t

Difference?

- Contextual bandit problem becomes K-armed bandit problem when
 - The action set A_t is unchanged and contains K actions for all t
 - The user u₁ (or the context) is the same for all t
- Also called context-free bandit problem

Users u₁ with age YOUNG and u₂ with age OLD



 u_1



 u_{2}

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Article Recommendation in Contextual Linear Bandit Setting

Users u₁ with age YOUNG and u₂ with age OLD



$$\mathbf{x_1} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$



$$\mathbf{x_2} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

θ_1 Retirement planning wishes vs. reality

- The Player Wizarding World of Harry Potter ride may conjure a new path for theme park rides
- θ_3 Elon Musk: 198,000 Tesla Model 3 Orders Received in 24 Hours
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Article Recommendation in Contextual Linear Bandit Setting

Linear Payoff = $x^T \theta$

Users u₁ with age YOUNG and u₂ with age OLD



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[0.1, 0.6] **Retirement planning wishes vs. reality**

The Player Wizarding World of Harry Potter [0.5, 0.1] ride may conjure a new path for theme park rides

[0.6,0.1] Elon Musk: 198,000 Tesla Model 3 Orders Received in 24 Hours

[0.9 , 0.2] **Not tired yet: Warriors top Spurs for 72nd win, set up date with history**

Article Recommendation in Contextual Linear Bandit Setting

Linear Payoff = $x^T \theta$

Users u₁ with age YOUNG and u₂ with age OLD



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LinUCB Algorithm

- Assumption: the payoff model is linear
 - Most Intuitive thought: Linear Model
 - Advantage: Confidence interval computed efficiently in closed form
- Tempting to apply UCB on general contextual bandit problems
 - asymptotic optimality
 - strong regret bound
 - → Called LinUCB algorithm.

Contextual Bandit

For each trail t=1,2,3..., T

- 1. Observe environment $x_{t,a} \in \mathbb{R}^d$, i.e. user u_t a set of actions \mathcal{A}_t and both their features
- 2. Choose an arm $a_t \in \mathcal{A}$ based on previous trails an receive payoff r_{t,a_t} .
- 3. Improve arm selection strategy with new observation $(\mathbf{x}_{t,a_t}, a_t, r_{t,a_t})$



Example: News Recommendation

For each time the news page is loaded t=1,2,3..., T

- 1. Arms or actions are the articles, which can be shown to the user. The environment could be user and article information.
- 2. If the aricle is clicked $r_{t,a_t} = 1$ otherwise 0.
- 3. Improve new article selection



Minimize expected regret, i.e

$$R_A(T) = \mathbb{E}\left[\sum_{t=1}^T r_{t,a_t^*}\right] - \mathbb{E}\left[\sum_{t=1}^T r_{t,a_t}\right]$$

Lecture 17: The Multi-Armed Bandit Problem

Two Models

- For convenience exposition, first describe simpler form
 - Disjoint linear model
- Then consider the general case
 - hybrid model
 - → LinUCB is a generic contextual bandit algorithm which applies to applications other than personalized news article recommendation.

Linear Disjoint Model

• We assume the expected payoff of an arm a is linear in its ddimentional feature $x_{t,a}$ with some unknown coefficient
vector θ_a^* ; namely for all t,

$$\mathbf{E}[r_{t,a}|\mathbf{x}_{t,a}] = \mathbf{x}_{t,a}^{\top} \boldsymbol{\theta}_a^*$$

• The model is called disjoint because the parameters are not shared among different arms.

"Disjoint" in example

Article Recommendation

Users u₁ with age YOUNG and u₂ with age OLD



 u_1



 U_2

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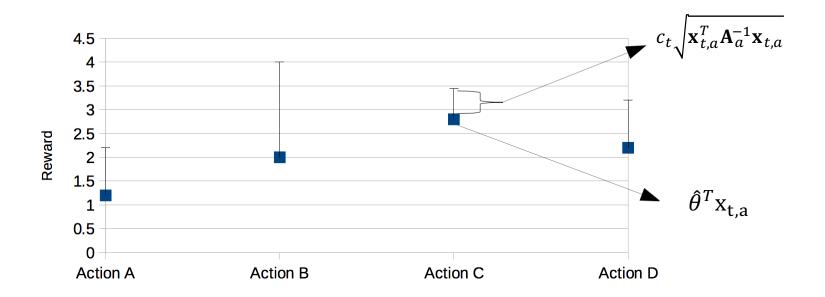
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Algorithm

Algorithm 1 LinUCB with disjoint linear models.

```
0: Inputs: c_t \in \mathbb{R}_+
  1: for t = 1, 2, 3, \dots, T do
            Observe features of all arms a \in \mathcal{A}_t: \mathbf{x}_{t,a} \in \mathbb{R}^d
            for all a \in \mathcal{A}_t do
  3:
                 if a is new then
  4:
                      \mathbf{A}_a \leftarrow \mathbf{I}_d (d-dimensional identity matrix)
  5:
 6:
                      \mathbf{b}_a \leftarrow \mathbf{0}_{d \times 1} (d-dimensional zero vector)
 7:
                end if
          \hat{\boldsymbol{\theta}}_a \leftarrow \mathbf{A}_a^{-1} \mathbf{b}_a
p_{t,a} \leftarrow \hat{\boldsymbol{\theta}}_a^{\top} \mathbf{x}_{t,a} + c_t \sqrt{\mathbf{x}_{t,a}^T \mathbf{A}_a^{-1} \mathbf{x}_{t,a}}
 9:
10:
            end for
11:
             Choose arm a_t = \arg \max_{a \in A_t} p_{t,a} with ties broken arbi-
            trarily, and observe a real-valued payoff r_t
            \mathbf{A}_{a_t} \leftarrow \mathbf{A}_{a_t} + \mathbf{x}_{t,a_t} \mathbf{x}_{t,a_t}^{	op}
12:
            \mathbf{b}_{a_t} \leftarrow \mathbf{b}_{a_t} + r_t \mathbf{x}_{t,a_t}
13:
14: end for
```

Visualization Representation



Lecture 17: The Multi-Armed Bandit Problem

Feature-free bandit v.s. linear bandit

Feature-free bandit

- $\bullet \ \mathbb{E}[r_{t,a}|x_{t,a}] = \mu_a^*.$
- μ_a^* is not known a priori.
- Confidence interval $C_{t,a}$

$$\{\mu_a: \frac{|\mu_a - \bar{\mu}_{t,a}|}{1/\sqrt{n_{t,a}}} \le \sqrt{2\log t}\}$$

0

$$a_t = \underset{a \in \{1, \dots, K\}}{\arg \max} \underset{\mu_a \in C_{t,a}}{\max} \mu_a$$
$$= \underset{a \in \{1, \dots, K\}}{\arg \max} \bar{\mu}_{t,a} + \sqrt{\frac{2 \log t}{n_{t,a}}}$$

Feature-free bandit v.s. linear bandit

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Linear bandit

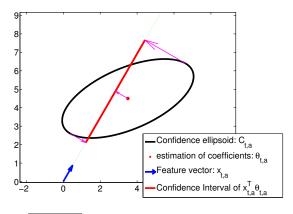
- $\bullet \ \mathbb{E}[r_{t,a}|x_{t,a}] = x_{t,a}^T \theta_a^*.$
- θ_a^* is not known a priori.
- ullet Confidence ellipsiod $C_{t,a}$

$$\{\theta_a: ||\theta_a - \hat{\theta}_{t,a}||_{A_{t,a}} \le c_t\}$$

where $||x||_A \equiv \sqrt{x^T A x}$.

$$a_{t} = \underset{a \in \{1, \dots, K\}}{\arg \max} \max_{\theta_{a} \in C_{t,a}} x_{t,a}^{T} \theta_{a}$$
$$= \underset{a \in \{1, \dots, K\}}{\arg \max} x_{t,a}^{T} \hat{\theta}_{t,a} + c_{t} \sqrt{x_{t,a}^{T} A_{t,a}^{-1} x_{t,a}}$$

Confidence ellipsiod $C_{t,a} = \{\theta_a : ||\theta_a - \hat{\theta}_{t,a}||_{A_{t,a}} \le c_t\}$



$$\begin{aligned} x_{t,a}^T \hat{\theta}_{t,a} + c_t \sqrt{x_{t,a}^T A_{t,a}^{-1} x_{t,a}} &= \max_{\theta_a} \quad x_{t,a}^T \theta_a \\ \text{s.t.} \quad (\theta_a - \hat{\theta}_{t,a})^T A_{t,a} (\theta_a - \hat{\theta}_{t,a}) \leq c_t \end{aligned}$$

Feature-free bandit = Linear bandit with $x_{t,a} \equiv 1, \theta_a = \mu_a$

Feature-free bandit

- $\bullet \ \mathbb{E}[r_{t,a}|x_{t,a}] = 1^T \mu_a^*.$
- μ_a^* is not known a priori.
- Confidence interval $C_{t,a}$

$$\{\mu_a: ||\mu_a - \bar{\mu}_{t,a}||_{n_{t,a}} \le \sqrt{2 \log t}\}$$

where $||\mu||_n \equiv \sqrt{\mu^T n \mu}$.

•

$$a_{t} = \underset{a \in \{1, ..., K\}}{\arg \max} \max_{\mu_{a} \in C_{t, a}} 1^{T} \mu_{a}$$
$$= \underset{a \in \{1, ..., K\}}{\arg \max} 1^{T} \bar{\mu}_{t, a} + \sqrt{\frac{2 \log t}{n_{t, a}}}$$

Linear bandit

- $\bullet \ \mathbb{E}[r_{t,a}|x_{t,a}] = x_{t,a}^T \theta_a^*.$
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A Bayesian approach to derive $\hat{\theta}_{t,a}$ and $A_{t,a}^{-1}$

• Gaussian prior $p_0(\theta_a) \sim \mathcal{N}(0, \lambda I_d)$.

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- Gaussian prior $p_0(\theta_a) \sim \mathcal{N}(0, \lambda I_d)$.
- $n_{t,a}$ noisy measurements: $\mathbf{y}_{t,a} \sim \mathcal{N}(\mathbf{D}_{t,a}\theta_a, \mathbf{I}_{n_{t,a}})$.

$$\begin{bmatrix} \vdots \\ \mathbf{y}_{t,a}(i) \\ \vdots \end{bmatrix} = \begin{bmatrix} \vdots \\ x_{i,a}^T \\ \vdots \end{bmatrix} \theta_a + \begin{bmatrix} \vdots \\ \eta_{i,a} \\ \vdots \end{bmatrix}$$

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• Posterior distribution $p_{t,a}(\theta_a) \sim \mathcal{N}(\hat{\theta}_{t,a}, A_{t,a}^{-1})$.

$$\hat{\theta}_{t,a} = (\mathbf{D}_{t,a}^T \mathbf{D}_{t,a} + \frac{1}{\lambda} I_d)^{-1} \underbrace{\mathbf{D}_{t,a}^T \mathbf{y}_{t,a}}_{\mathbf{b}_{t,a}},$$

$$A_{t,a} = \mathbf{D}_{t,a}^T \mathbf{D}_{t,a} + \frac{1}{\lambda} I_d.$$

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- Gaussian prior $p_0(\theta_a) \sim \mathcal{N}(0, \lambda I_d)$.
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$$A_{t,a} = \mathbf{D}_{t,a}^T \mathbf{D}_{t,a} + \frac{1}{\lambda} I_d.$$

• The reward $x_{t,a}^T \theta_a \sim \mathcal{N}(x_{t,a}^T \hat{\theta}_{t,a}, x_{t,a}^T A_{t,a}^{-1} x_{t,a})$. The upper confidence bound (UCB) is $x_{t,a}^T \hat{\theta}_{t,a} + c_t \sqrt{x_{t,a}^T A_{t,a}^{-1} x_{t,a}}$.

A general form of linear bandit

Disjoint linear model

$$\bullet \ \mathbb{E}[r_{t,a}|x_{t,a}] = x_{t,a}^T \theta_a^*.$$

•

$$a_t = \underset{a \in \{1, \dots, K\}}{\arg \max} \max_{\theta_a \in C_{t,a}} x_{t,a}^T \theta_a$$

A general linear model

$$\bullet \ \mathbb{E}[r_t|x_t] = x_t^T \theta^*.$$

0

$$x_t = \underset{x \in \mathcal{A}_t}{\operatorname{arg \, max}} \ \underset{\theta \in C_t}{\operatorname{max}} x^T \theta$$

A general form of linear bandit

Disjoint linear model

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A general linear model

 $\bullet \ \mathbb{E}[r_t|x_t] = x_t^T \theta^*.$

0

$$x_t = \underset{x \in \mathcal{A}_t}{\operatorname{arg\,max}} \quad \underset{\theta \in C_t}{\operatorname{max}} x^T \theta$$

$$\theta = \begin{bmatrix} \theta_1 \\ \vdots \\ \theta_a \\ \vdots \\ \theta_K \end{bmatrix}, \quad \mathcal{A}_t = \left\{ \begin{bmatrix} \vdots \\ 0 \\ x_{t,a} \\ 0 \\ \vdots \end{bmatrix} : a = 1, 2, \dots, K \right\}$$

A hybrid linear model

A hybrid linear model

• $\mathbb{E}[r_{t,a}|z_{t,a},x_{t,a}] = z_{t,a}^T \beta^* + x_{t,a}^T \theta_a^*$.

•

$$a_t = \underset{a \in \{1, \dots, K\}}{\operatorname{arg max}} \max_{\beta, \theta_a \in C_t} z_{t, a}^T \beta + x_{t, a}^T \theta_a$$

A general linear model

 $\bullet \ \mathbb{E}[r_t|x_t] = x_t^T \theta^*.$

$$x_t = \underset{x \in \mathcal{A}_t}{\arg \max} \ \underset{\theta \in C_t}{\max} \ x^T \theta$$

$$\theta = \begin{bmatrix} \beta \\ \theta_1 \\ \vdots \\ \theta_a \\ \vdots \\ \theta_K \end{bmatrix}, \quad \mathcal{A}_t = \begin{Bmatrix} \begin{bmatrix} z_{t,a} \\ \vdots \\ 0 \\ x_{t,a} \\ 0 \\ \vdots \end{bmatrix} : a = 1, 2, \dots, K \end{Bmatrix}$$

A general form of linear bandit, continued

Disjoint linear model

$$a_t = \underset{a \in \{1, \dots, K\}}{\operatorname{arg max}} \max_{\theta_a \in C_{t,a}} x_{t,a}^T \theta_a$$

0

$$C_{t,a} = \{\theta_a : ||\theta_a - \hat{\theta}_{t,a}||_{A_{t,a}} \le c_t\}$$

•

$$\hat{\theta}_{t,a} = (\mathbf{D}_{t,a}^T \mathbf{D}_{t,a} + \frac{1}{\lambda} I_d)^{-1} \mathbf{D}_{t,a}^T \mathbf{y}_{t,a},$$

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A general form of linear bandit, continued

Disjoint linear model

$$a_t = \underset{a \in \{1, \dots, K\}}{\operatorname{arg max}} \max_{\theta_a \in C_{t,a}} x_{t,a}^T \theta_a$$

•

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•

$$\begin{split} \hat{\theta}_{t,a} &= (\mathbf{D}_{t,a}^T \mathbf{D}_{t,a} + \frac{1}{\lambda} I_d)^{-1} \mathbf{D}_{t,a}^T \mathbf{y}_{t,a} \,, \\ A_{t,a} &= \mathbf{D}_{t,a}^T \mathbf{D}_{t,a} + \frac{1}{\lambda} I_d \,. \end{split}$$

A general linear model

$$x_t = \underset{x \in \mathcal{A}_t}{\operatorname{arg\,max}} \ \underset{\theta \in C_t}{\operatorname{max}} x^T \theta$$

•

$$C_t = \{\theta : ||\theta - \hat{\theta}_t||_{A_t} \le c_t\}$$

•

$$\hat{\theta}_t = (\mathbf{D}_t^T \mathbf{D}_t + \frac{1}{\lambda} I_d)^{-1} \mathbf{D}_t^T \mathbf{y}_t,$$

$$A_t = \mathbf{D}_t^T \mathbf{D}_t + \frac{1}{\lambda} I_d.$$

An $O(d\sqrt{T})$ regret bound

Theorem (Theorem 2 + Theorem 3 in APS_2011)

Assume that

- **1** The measurement noise η_t is independent of everything and is σ -sub-Gaussian for some $\sigma > 0$, i.e., $\mathbb{E}[e^{\lambda \eta_t}] \leq \exp(\frac{\lambda^2 \sigma^2}{2})$ for all $\lambda \in \mathbf{R}$.
- **3** For all t and all $x \in \mathcal{A}_t$, $x^T \theta^* \in [-1, 1]$.

Then, for any $\delta > 0$, with probability at least $1 - \delta$, for all $t \ge 0$,

lacktriangledown θ^* lies in the confidence ellipsoid

$$C_t = \left\{ \theta : \|\theta - \hat{\theta}_t\|_{A_t} \le \frac{c_t}{\delta} := \sigma \sqrt{\log \det A_t + d \log \lambda + 2 \log \frac{1}{\delta}} + \frac{\|\theta^*\|}{\sqrt{\lambda}} \right\}$$

The regret of the linUCB algorithm satisfies

$$R_{t} = \underbrace{\sqrt{8t}}_{\text{I}} \underbrace{\sqrt{\log \det A_{t} + d \log \lambda}}_{\text{II}} \underbrace{\left(\sigma \sqrt{\log \det A_{t} + d \log \lambda + 2 \log \frac{1}{\delta} + \frac{\|\theta^{*}\|}{\sqrt{\lambda}}}\right)}_{\text{III}: c_{t}}$$

An $O(d\sqrt{T})$ regret bound

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 \bullet lies in the confidence ellipsoid

$$C_t = \left\{ \theta : \|\theta - \hat{\theta}_t\|_{A_t} \le \frac{c_t}{\delta} := \sigma \sqrt{\log \det A_t + d \log \lambda + 2 \log \frac{1}{\delta}} + \frac{\|\theta^*\|}{\sqrt{\lambda}} \right\}$$

The regret of the linUCB algorithm satisfies

$$R_t = \underbrace{\sqrt{8t}}_{\text{I}} \underbrace{\sqrt{\log \det A_t + d \log \lambda}}_{\text{II}} \underbrace{\left[\sigma \sqrt{\log \det A_t + d \log \lambda + 2 \log \frac{1}{\delta}} + \frac{\|\theta^*\|}{\sqrt{\lambda}}\right]}_{\text{II}: c_t}$$

Lemma (Determinant-Trace Inequality, Lemma 10 in APS_2011)

If for all $t \ge 0$, $||x_t||_2 \le L$ then

$$\log \det A_t \le d \log(\frac{1}{\lambda} + \frac{tL^2}{d})$$

.

The ♥ of the proof

We consider the high probability event $\theta^* \in C_t$ for all $t \ge 0$.

$$\begin{split} r_t &= \langle x_t^*, \theta^* \rangle - \langle x_t, \theta^* \rangle & \quad x_t, \tilde{\theta}_t = \underset{x \in \mathcal{A}_t}{\arg\max} \underset{\theta \in C_t}{\max} \langle x, \theta \rangle \\ &\leq \langle x_t, \tilde{\theta}_t \rangle - \langle x_t, \theta^* \rangle & \quad \theta^* \in C_t \\ &= \langle x_t, \tilde{\theta}_t - \theta^* \rangle \\ &= \langle x_t, \hat{\theta}_t - \theta^* \rangle + \langle x_t, \tilde{\theta}_t - \hat{\theta}_t \rangle \\ &\leq ||x_t||_{A_t^{-1}} ||\hat{\theta}_t - \theta^*||_{A_t} + ||x_t||_{A_t^{-1}} ||\tilde{\theta}_t - \hat{\theta}_t||_{A_t} & \text{Cauchy-Schwarz} \\ &\leq 2c_t ||x_t||_{A_t^{-1}} & \quad \theta^*, \tilde{\theta}_t \in C_t = \{\theta: ||\theta - \hat{\theta}_t||_{A_t} \leq c_t \} \end{split}$$

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Since $x^T \theta^* \in [-1, 1]$ for all $x \in \mathcal{A}_t$, then we have $r_t \leq 2$. Therefore,

$$r_t \le \min\{2c_t ||x_t||_{A_t^{-1}}, 2\} \le 2c_t \min\{||x_t||_{A_t^{-1}}, 1\}$$

The ♥ of the proof, continued

$$r_t^2 \le 4c_t^2 \min\{\|x_t\|_{A_t^{-1}}^2, 1\} \tag{1}$$

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Consider the regret $R_T \equiv \sum_{t=1}^T r_t$,

$$\begin{split} R_T & \leq \sqrt{\frac{T}{\sum_{t=1}^T r_t^2}} \underbrace{ \frac{\leq}{\text{By (1)}}} \sqrt{\frac{T}{\sum_{t=1}^T 4c_t^2 \min\{\|x_t\|_{A_t^{-1}}^2, 1\}}} \\ & \leq 2\underbrace{\sqrt{T}}_{\text{II}} \underbrace{c_T}_{\text{III}} \underbrace{\sqrt{\sum_{t=1}^T \min\{\|x_t\|_{A_t^{-1}}^2, 1\}}}_{\text{II}} \qquad c_t \text{ is monotonically increasing.} \end{split}$$

The ♥ of the proof, continued

$$r_t^2 \le 4c_t^2 \min\{\|x_t\|_{A_t^{-1}}^2, 1\} \tag{1}$$

Consider the regret $R_T \equiv \sum_{t=1}^{T} r_t$,

$$\begin{split} R_T & \leq \sqrt{T \sum_{t=1}^T r_t^2} \quad \underbrace{\leq}_{\text{By (1)}} \quad \sqrt{T \sum_{t=1}^T 4c_t^2 \min\{\|x_t\|_{A_t^{-1}}^2, 1\}} \\ & \leq 2 \underbrace{\sqrt{T}}_{\text{II}} \underbrace{c_T}_{\text{III}} \underbrace{\sqrt{\sum_{t=1}^T \min\{\|x_t\|_{A_t^{-1}}^2, 1\}}}_{\text{II}} \quad c_t \text{ is monotonically increasing.} \end{split}$$

Since $x \le 2 \log(1 + x)$ for $x \in [0, 1]$, we have

$$\sum_{t=1}^{T} \min\{\|x_t\|_{A_t^{-1}}^2, 1\} \le 2 \sum_{t=1}^{T} \log(1 + \|x_t\|_{A_t^{-1}}^2) = 2(\log \det A_t + d \log \lambda).$$

The last equality is proved in Lemma 11 in APS_2011.

How do we evaluate the performance of a recommendation algorithm?

- Can we just run the algorithm on "live" data?
- Build a simulator to model the bandit process, evaluate the algorithm based on the simulated data?

How do we evaluate the performance of a recommendation algorithm?

- Can we just run the algorithm on "live" data?
 Difficult logistically.
- Build a simulator to model the bandit process, evaluate the algorithm based on the simulated data? May introduce bias from the simulator.

Yahoo! Today Module! (random article)

- 0: Inputs: T > 0, algorithm π , stream of events
- $1: h_0 = 0, R_0 = 0$
- 2 : for t = 1, 2, ..., T do
- 3: repeat
- 4: Get next event $(x_1, ..., x_K, a, r_a)$
- 5: until $\pi(h_{t-1}, (x_1, ..., x_K)) = a$
- 6: $h_t \leftarrow \text{add}(h_{t-1}, (x_1, ..., x_K, a, r_a))$
- $7: \quad R_t \leftarrow R_{t-1} + r_a$
- 8: end for
- 9 : Output R_t/T

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No bias! About T events are accepted from TK trails.

Algorithm Evaluation (data collection)

Yahoo News ...

Randomly shoot user an article *a* as highlighted news.











Kerry arrives in Japan for landmark Hiroshima visit

Cruz rails against Trump as Republican Jews ponder…

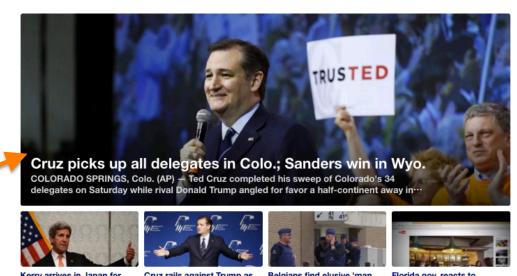
Belgians find elusive 'man in the hat' from airport...

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in the hat' from airport...

Starbucks critic with attac...

Republican Jews ponder···

This event contains article a, feature vector X, and response r = 1/0.

landmark Hiroshima visit

Accept this event iff algorithm predicts the same article a.

In Yahoo's data base, either a user or article is depicted by hundreds raw features.

Need to reduce the feature dimensions.













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Article	Long	Domestic	Tech	Politics	•
ϕ_a	1	1	0	1	•••

Raw $\phi_{m{u}}$

User	Gender	Age>20	Age>40	Student	
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Raw	ϕ_a
INGVV	, ~

Article	Long	Domestic	Tech	Politics	•••
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Raw $\phi_{m{u}}$

User	Gender	Age>20	Age>40	Student	•••
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Suppose there's a weight matrix W, st. the probability of user clicking on article a is: $P = \phi_u^T W \phi_a$

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Logistic Regression to get W

K-means method to find clusters/groups of the users.

$$\psi_u \equiv \phi_u^T W$$
 (Cluster this projected feature vector.)

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Logistic Regression to get W

K-means method to find clusters/groups of the users.

$$\psi_u \equiv \phi_u^T W$$
 (Cluster this projected feature vector.)

• The constructed feature vector for a user would be the possibilities of being in different groups.

Denote as: $x_{t,a}$

- The same procedure can be applied to the article and get the constructed feature vector.
- \triangleright <u>Disjointed LinUCB</u>, use $x_{t,a}$ as input data.
- ➤ <u>Hybrid model</u>, the outer product of constructed user and article feature vectors is also included as global features.

For example, we have binary raw feature vectors:

$$\phi_a = (1, 1, 0, 1, 1, ...)$$
 $\phi_u = (1, 1, 0, 1, 0, ...)$

For example, we have binary raw feature vectors for user and article:

$$\phi_a = (1, 1, 0, 1, 1, ...)$$
 $\phi_u = (1, 1, 0, 1, 0, ...)$

• After clustering:

User, $x_{t,a}$

Group	Α	В	С	D	Е
Membership	0.2	0.1	0.35	0.3	0.05

Article

Group	1	2	3	4	5
Membership	0.7	0.05	0.15	0.05	0.05

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- The <u>outer product</u> of the two constructed feature vectors is: $z_{t,a}$ (25 dimensional here)
- Hybrid model: $E[r_{t,a}|x_{t,a}] = z_{t,a}^T \beta^* + x_{t,a}^T \theta_a^*$

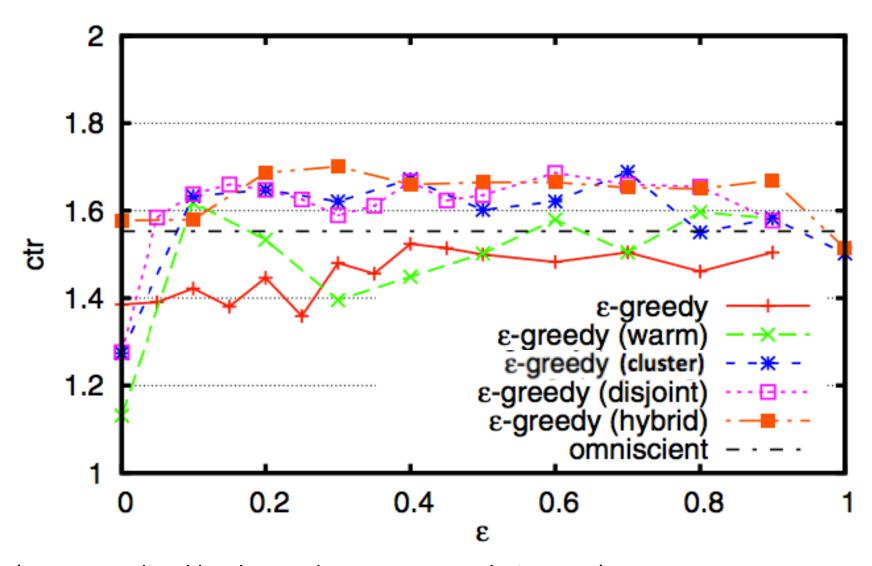
Remove this term will get back to disjointed LinUCB

Without utilizing features:

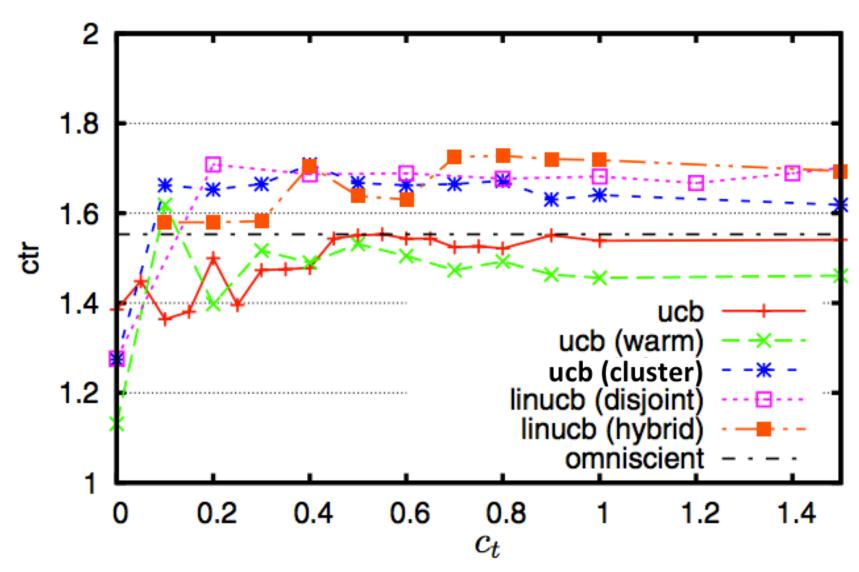
- Purely Random
- E-greedy
- UCB
- Omniscient

Algorithms with features:

- E-greedy (run on different clusters)
- E-greedy (hybrid, epoch greedy)
- UCB (cluster)
- LinUCB (disjoint)
- LinUCB (hybrid)



(CTR normalized by the random recommendation CTR)



(CTR normalized by the random recommendation CTR)

Conclusion

For multi-armed bandits problem

UCB algorithm without feature has regret bound:

$$R_T = O(\frac{K}{\epsilon} \ln T)$$

LinUCB using feature vectors has regret bound:

$$R_T = O(D\sqrt{T})$$

- Evaluate using Yahoo Front Page Today Module data.
- Introducing contextual information (features) to the recommendation algorithm, the CTR (reward) has been improved by about 10%.

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