

Machine Learning & Data Mining

CS/CNS/EE 155

Lecture 9: Conditional Random Fields

Announcements

- Homework 5 released
 - Skeleton code available on Moodle
 - Due in 2 weeks (2/16)
- Kaggle competition closes 2/9
 - SHORT report due 2/11 via Moodle
 - Submit as a group
- Nothing due week of 2/23

Today

- Recap of Sequence Prediction
- **Conditional Random Fields**
 - Sequential version of logistic regression
 - Analogous to how HMMs generalize Naïve Bayes
 - Discriminative sequence prediction
 - Learns to optimize $P(y|x)$ for sequences

Recap: Sequence Prediction

- Input: $x = (x^1, \dots, x^M)$
- Predict: $y = (y^1, \dots, y^M)$
 - Each y^i one of L labels.

• $x = \text{“Fish Sleep”}$

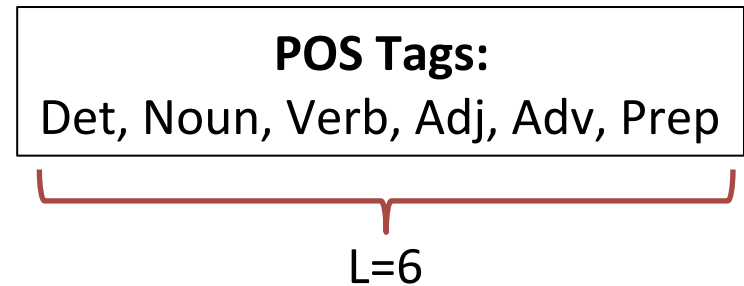
• $y = (N, V)$

• $x = \text{“The Dog Ate My Homework”}$

• $y = (D, N, V, D, N)$

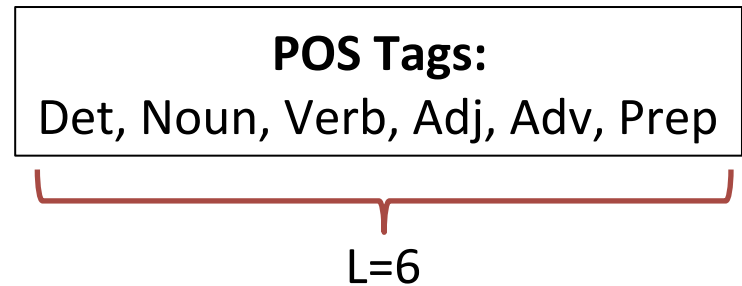
• $x = \text{“The Fox Jumped Over The Fence”}$

• $y = (D, N, V, P, D, N)$



Recap: General Multiclass

- $x = \text{“Fish sleep”}$
- $y = (N, V)$



- Multiclass prediction:
 - All possible length-M sequences as different class
 - (D, D), (D, N), (D, V), (D, Adj), (D, Adv), (D, Pr)
 - (N, D), (N, N), (N, V), (N, Adj), (N, Adv), ...
- L^M classes!
 - Length 2: $6^2 = 36!$

Recap: General Multiclass

- $x = \text{"Fish sleep"}$
- $y = (N, V)$

POS Tags:
Det, Noun, Verb, Adj, Adv, Prep

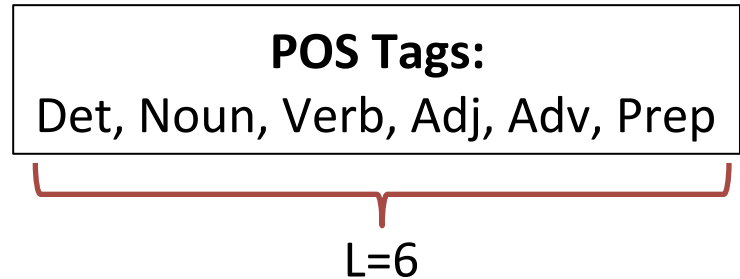


L=6

- M
Can Model Everything!
(In Theory)
- L
Exponential Explosion in #Classes!
(Not Tractable)

Recap: Independent Multiclass

$x = \text{"I fish often"}$

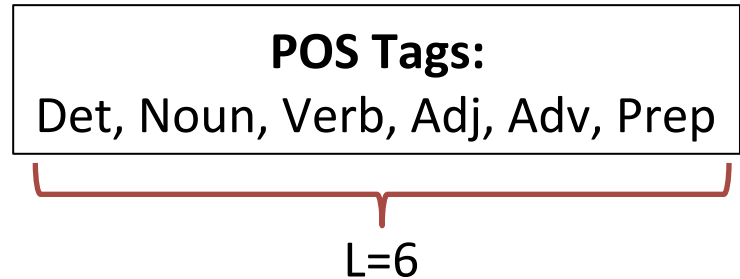


- Treat each word independently (assumption)
 - Independent multiclass prediction per word
 - Predict for $x = \text{"I"}$ independently
 - Predict for $x = \text{"fish"}$ independently
 - Predict for $x = \text{"often"}$ independently
 - Concatenate predictions.

Assume pronouns are nouns for simplicity.

Recap: Independent Multiclass

$x = \text{"I fish often"}$



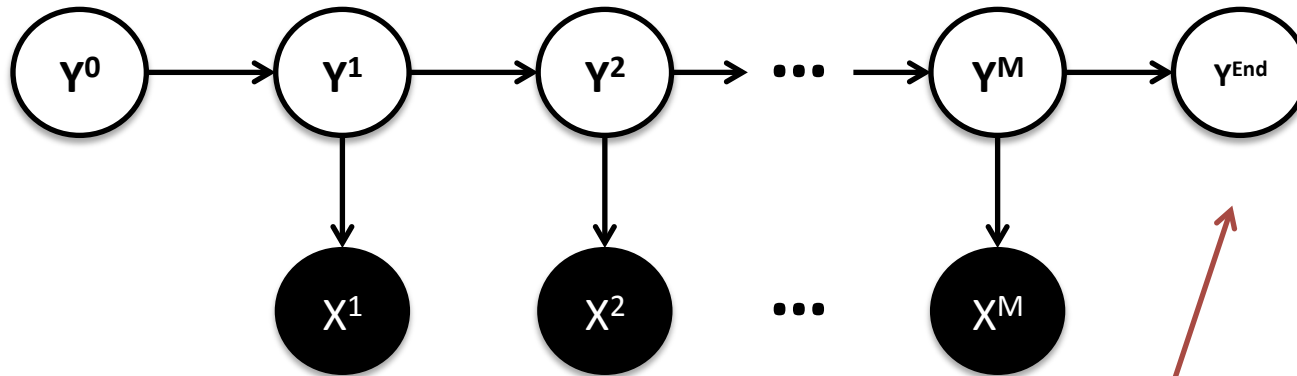
#Classes = #POS Tags
(6 in our example)

Solvable using standard multiclass prediction.
But ignores context!

Recap: 1st Order HMM

- $x = (x^1, x^2, x^3, x^4, \dots, x^M)$ (sequence of words)
- $y = (y^1, y^2, y^3, y^4, \dots, y^M)$ (sequence of POS tags)
- $P(x^i | y^i)$ Probability of state y^i generating x^i
- $P(y^{i+1} | y^i)$ Probability of state y^i transitioning to y^{i+1}
- $P(y^1 | y^0)$ y^0 is defined to be the Start state
- $P(\text{End} | y^M)$ Prior probability of y^M being the final state
 - Not always used

Graphical Model Representation



Optional

$$P(x, y) = P(\text{End} | y^M) \prod_{i=1}^M P(y^i | y^{i-1}) \prod_{i=1}^M P(x^i | y^i)$$

HMM Matrix Formulation

$$P(x, y) = P(END | y^M) \prod_{j=1}^M P(x^j | y^j) P(y^j | y^{j-1})$$

$$= A_{END, y^M} \prod_{j=1}^M A_{y^j y^{j-1}} O_{y^j, x^j}$$

Transition Probabilities

Emission Probabilities
(Observation Probabilities)

Recap: 1st-Order Sequence Models

- General multiclass:
 - Unique scoring function per entire seq.
 - Very intractable
- Independent multiclass
 - Scoring function per token, apply to each token in seq.
 - Ignores context, low accuracy
- **First-order models**
 - **Scoring function per pair of tokens.**
 - **“Sweet spot” between fully general & ind. multiclass**

Recap: Naïve Bayes & HMMs

- Naïve Bayes:

$$P(x, y) = P(y) \prod_{d=1}^D P(x^d | y)$$

- Hidden Markov Models:

$$P(x, y) = P(\text{End} | y^M) \underbrace{\prod_{j=1}^M P(y^j | y^{j-1})}_{P(y)} \prod_{i=1}^M P(x^i | y^i)$$

“Naïve” Generative Independence Assumption

- **HMMs \approx 1st order variant of Naïve Bayes!**
(just one interpretation...)

Recap: Generative Models

- Joint model of (x,y) :
 - Compact & easy to train...
 - ...with ind. assumptions
 - E.g., Naïve Bayes & HMMs

$$P(x, y)$$

Θ often used to denote all parameters of model

- Maximize Likelihood Training:

$$\operatorname{argmax}_{\Theta} \prod_{i=1}^N P(x_i, y_i)$$

- Mismatch w/ prediction goal:
 - But hard to maximize $P(y|x)$

$$\operatorname{argmax}_y P(y|x)$$

$$S = \{(x_i, y_i)\}_{i=1}^N$$

Learn Conditional Prob.?

- Weird to train to maximize:

$$\operatorname{argmax}_{\Theta} \prod_{i=1}^N P(x_i, y_i)$$

$$S = \{(x_i, y_i)\}_{i=1}^N$$

- When goal should be to maximize:

$$\operatorname{argmax}_{\Theta} \prod_{i=1}^N P(y_i | x_i) = \operatorname{argmax}_{\Theta} \prod_{i=1}^N \frac{P(x_i, y_i)}{P(x_i)}$$

Breaks independence!

Can no longer use count statistics

~~$$P(x^d = a | y = z) = \frac{\sum_{i=1}^N 1_{[(y_i=z) \wedge (x_i^d=a)]}}{\sum_{i=1}^N 1_{[y_i=z]}}$$~~

$$p(x) = \sum_y P(x, y) = \sum_y P(y)P(x | y)$$

Both HMMs & Naïve Bayes suffer this problem!

Learn Conditional Prob.?

- Weird to train to maximize:

$$\prod_{i=1}^N P(x_i | y_i)$$

In general, you should maximize the likelihood of the model you define!

So if you define joint model $P(x,y)$, then maximize $P(x,y)$ on training data.

B
C

~~$$P(x^d = a | y = z) = \frac{\sum_{i=1}^N \mathbb{1}_{[y_i=z] \wedge (x_i^d=a)}}{\sum_{i=1}^N \mathbb{1}_{[y_i=z]}}$$~~

Both HMMs & Naïve Bayes suffer this problem!

Generative vs Discriminative

- Generative Models:

Hidden Markov Models
Naïve Bayes

- Joint Distribution: $P(x,y)$ ← Mismatch!
- Uses Bayes's Rule to predict: $\operatorname{argmax}_y P(y|x)$ ↗
- Can generate new samples (x,y)

- Discriminative Models:

Conditional Random Fields
Logistic Regression

- Conditional Distribution: $P(y|x)$ ← Same thing!
- Can directly to predict: $\operatorname{argmax}_y P(y|x)$ ↙

- Both trained via Maximum Likelihood

First Try

(for classifying a single y)

- Model $P(y|x)$ for every possible x

$P(y=1 x)$	x^1	x^2
0.5	0	0
0.7	0	1
0.2	1	0
0.4	1	1

- Train by counting frequencies
- **Exponential in # input variables!**
 - Need to assume something... what?

Log Linear Models!

(Logistic Regression)

$$P(y | x) = \frac{\exp\{w_y^T x - b_y\}}{\sum_k \exp\{w_k^T x - b_k\}} \quad \begin{array}{l} x \in R^D \\ y \in \{1, 2, \dots, L\} \end{array}$$

- “Log-Linear” assumption
 - Model representation to linear in x
 - Most common discriminative probabilistic model

Prediction:

$$\operatorname{argmax}_y P(y | x)$$

Training:

$$\operatorname{argmax}_{\Theta} \prod_{i=1}^N P(y_i | x_i)$$

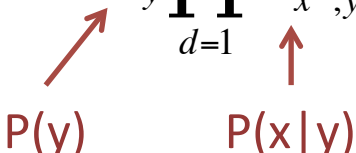
← **Match!** →

Naïve Bayes vs Logistic Regression

- Naïve Bayes:

- Strong ind. assumptions
- Super easy to train...
- ...but mismatch with prediction

$$P(x, y) = A_y \prod_{d=1}^D O_{x^d, y}^d$$


 $P(y)$ $P(x|y)$

- Logistic Regression:

- “Log Linear” assumption
 - Often more flexible than Naïve Bayes
- Harder to train (gradient desc.)...
- ...but matches prediction

$$P(y|x) = \frac{\exp\{w_y^T x - b_y\}}{\sum_k \exp\{w_k^T x - b_k\}}$$

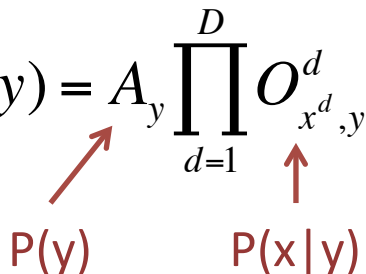
$$x \in R^D$$
$$y \in \{1, 2, \dots, L\}$$

Naïve Bayes vs Logistic Regression

- NB has L parameters for P(y) (i.e., A)
- LR has L parameters for bias b
- NB has L*D parameters for P(x|y) (i.e, O)
- LR has L*D parameters for w
- **Same number of parameters!**

Naïve Bayes

$$P(x, y) = A_y \prod_{d=1}^D O_{x^d, y}^d$$



$P(y)$ $P(x|y)$

Logistic Regression

$$P(y | x) = \frac{e^{w_y^T x - b_y}}{\sum_k e^{w_k^T x - b_k}}$$

$$x \in \{0, 1\}^D$$
$$y \in \{1, 2, \dots, L\}$$

Naïve Bayes vs Logistic Regression

Intuition:

Both models have same “capacity”

NB spends a lot of capacity on $P(x)$

LR spends all of capacity on $P(y|x)$

No Model Is Perfect!

(Especially on finite training set)

NB will trade off $P(y|x)$ with $P(x)$

LR will fit $P(y|x)$ as well as possible

Conditional Random Fields

Sequential Version of Logistic Regression

“Log-Linear” 1st Order Sequential Model

$$P(y | x) = \frac{1}{Z(x)} \exp \left\{ \sum_{j=1}^M \left(A_{y^j, y^{j-1}} + O_{y^j, x^j} \right) \right\}$$

$$Z(x) = \sum_{y'} \exp \{ F(y', x) \} \quad \text{aka “Partition Function”}$$

$$F(y, x) \equiv \sum_{j=1}^M \left(A_{y^j, y^{j-1}} + O_{y^j, x^j} \right) \quad \text{Scoring Function}$$

Scoring transitions Scoring input features

$$P(y | x) = \frac{\exp \{ F(y, x) \}}{Z(x)} \quad \log P(y | x) = F(y, x) - \log(Z(x))$$

y^0 = special start state, excluding end state

- $x = \text{"Fish Sleep"}$
- $y = (N, V)$

$$P(y | x) = \frac{1}{Z(x)} \exp \left\{ \sum_{j=1}^M (A_{y^j, y^{j-1}} + O_{y^j, x^j}) \right\}$$

$A_{N,V}$ →

	$A_{N,*}$	$A_{V,*}$
$A_{*,N}$	-2	1
$A_{*,V}$	2	-2
$A_{*,Start}$	1	-1

← $W_{V,Fish}$

	$O_{N,*}$	$O_{V,*}$
$O_{*,Fish}$	2	1
$O_{*,Sleep}$	1	0

$$P(N, V | \text{"Fish Sleep"}) = \frac{1}{Z(x)} \exp \{ A_{N,Start} + O_{N,Fish} + A_{V,N} + O_{V,Sleep} \} = \frac{1}{Z(x)} \exp \{ 4 \} \approx 0.66$$

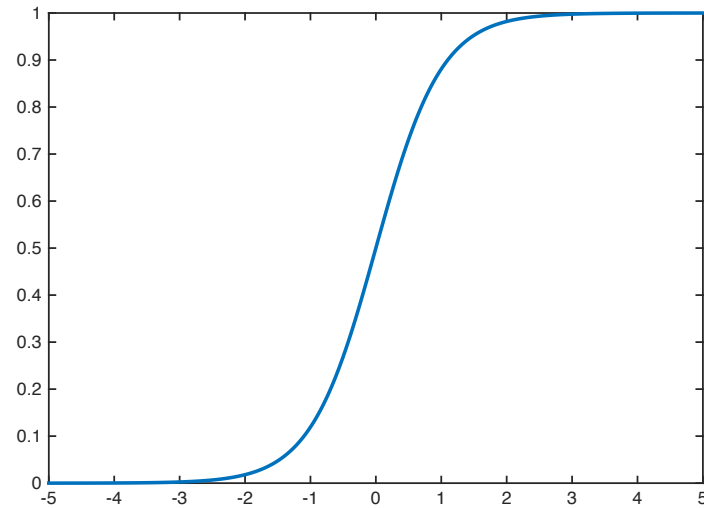
$$Z(x) = \text{Sum} \left(\begin{array}{|c|c|} \hline \mathbf{y} & \mathbf{\exp(F(y,x))} \\ \hline (N,N) & \exp(1+2-2+1) = \exp(2) \\ \hline (N,V) & \exp(1+2+2+0) = \exp(4) \\ \hline (V,N) & \exp(-1+1+2+1) = \exp(3) \\ \hline (V,V) & \exp(-1+1-2+0) = \exp(-2) \\ \hline \end{array} \right)$$

- $x = \text{"Fish Sleep"}$
- $y = (N, V)$

$$P(N, V | \text{"Fish Sleep"}) = \frac{1}{Z(x)} \exp\{F(x, y)\}$$

$P(N, V | \text{"Fish Sleep"})$

*hold other parameters fixed




$F(y, x)$

Basic Conditional Random Field

- Directly models $P(y|x)$
 - Discriminative
 - Log linear assumption
 - Same #parameters as HMM
 - 1st Order Sequential LR

CRF spends all model capacity on $P(y|x)$, rather than $P(x,y)$



$$F(y, x) \equiv \sum_{j=1}^M (A_{y^j, y^{j-1}} + O_{y^j, x^j})$$

$$P(y|x) = \frac{\exp\{F(y, x)\}}{\sum_{y'} \exp\{F(y', x)\}}$$

- **How to Predict?**
- **How to Train?**
- **Extensions?**

$$\log P(y|x) = F(y, x) - \log \left(\sum_{y'} \exp\{F(y', x)\} \right)$$

Predict via Viterbi

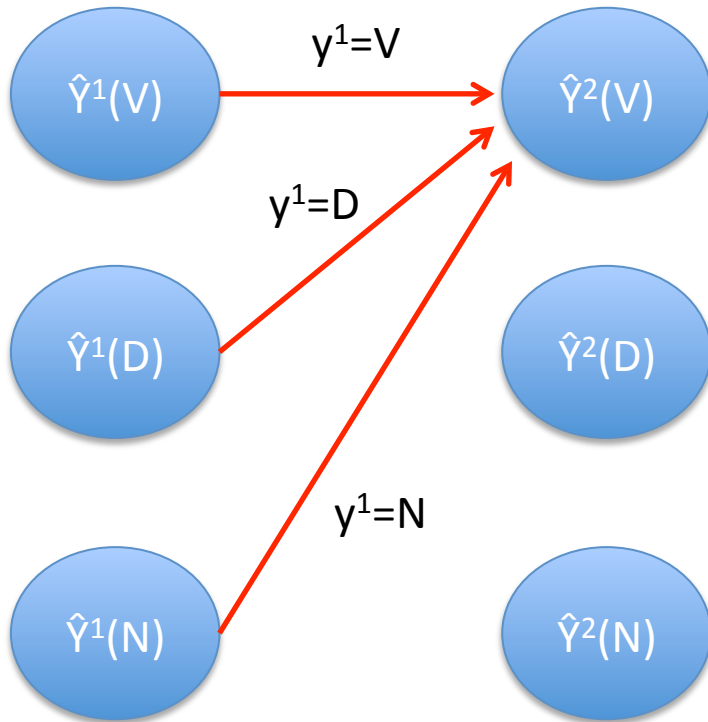
$$\begin{aligned}
 \operatorname{argmax}_y P(y | x) &= \operatorname{argmax}_y \log P(y | x) = \operatorname{argmax}_y F(y, x) \\
 &= \operatorname{argmax}_y \sum_{j=1}^M \left(A_{j, y^{j-1}} + O_{y^j, x^j} \right)
 \end{aligned}$$

Scoring transitions
Scoring observations

Maintain length-k prefix solutions	$\hat{Y}^k(T) = \left(\operatorname{argmax}_{y^{1:k-1}} F(y^{1:k-1} \oplus T, x^{1:k}) \right) \oplus T$
Recursively solve for length-(k+1) solutions	$ \begin{aligned} \hat{Y}^{k+1}(T) &= \left(\operatorname{argmax}_{y^{1:k} \in \{\hat{Y}^k(T)\}_T} F(y^{1:k} \oplus T, x^{1:k+1}) \right) \oplus T \\ &= \left(\operatorname{argmax}_{y^{1:k} \in \{\hat{Y}^k(T)\}_T} F(y^{1:k}, x^{1:k}) + A_{T, y^k} + O_{T, x^{k+1}} \right) \oplus T \end{aligned} $
Predict via best length-M solution	$\operatorname{argmax}_y F(y, x) = \operatorname{argmax}_{y \in \{\hat{Y}^M(T)\}_T} F(y, x)$

$$\text{Solve: } \hat{Y}^2(V) = \left(\underset{y^1 \in \{\hat{Y}^1(T)\}_T}{\operatorname{argmax}} F(y^1, x^1) + A_{V, y^1} + O_{V, x^2} \right) \oplus V$$

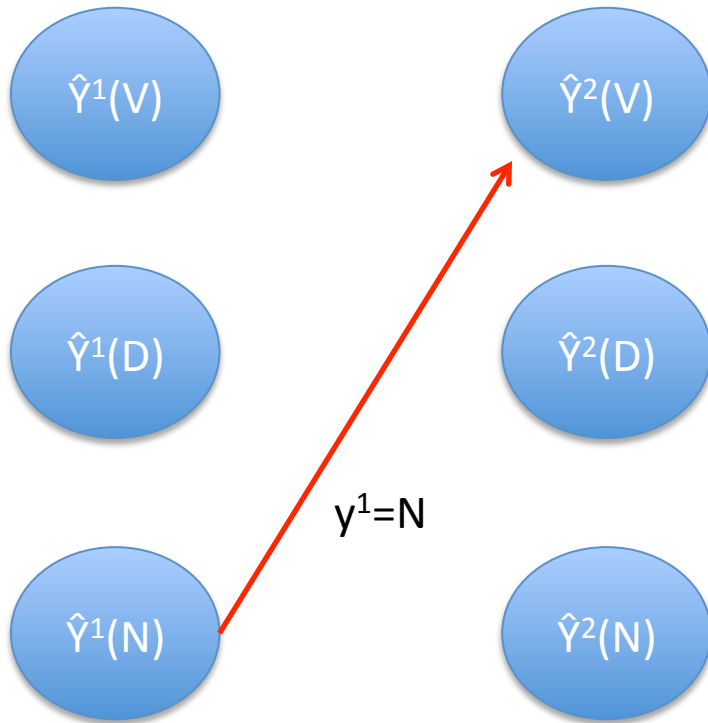
Store each
 $\hat{Y}^1(T)$ & $F(\hat{Y}^1(T), x)$



$\hat{Y}^1(T)$ is just T

Solve: $\hat{Y}^2(V) = \left(\operatorname{argmax}_{y^1 \in \{\hat{Y}^1(T)\}_T} F(y^1, x^1) + A_{V, y^1} + O_{V, x^2} \right) \oplus V$

Store each $\hat{Y}^1(T)$ & $F(\hat{Y}^1(T), x^1)$



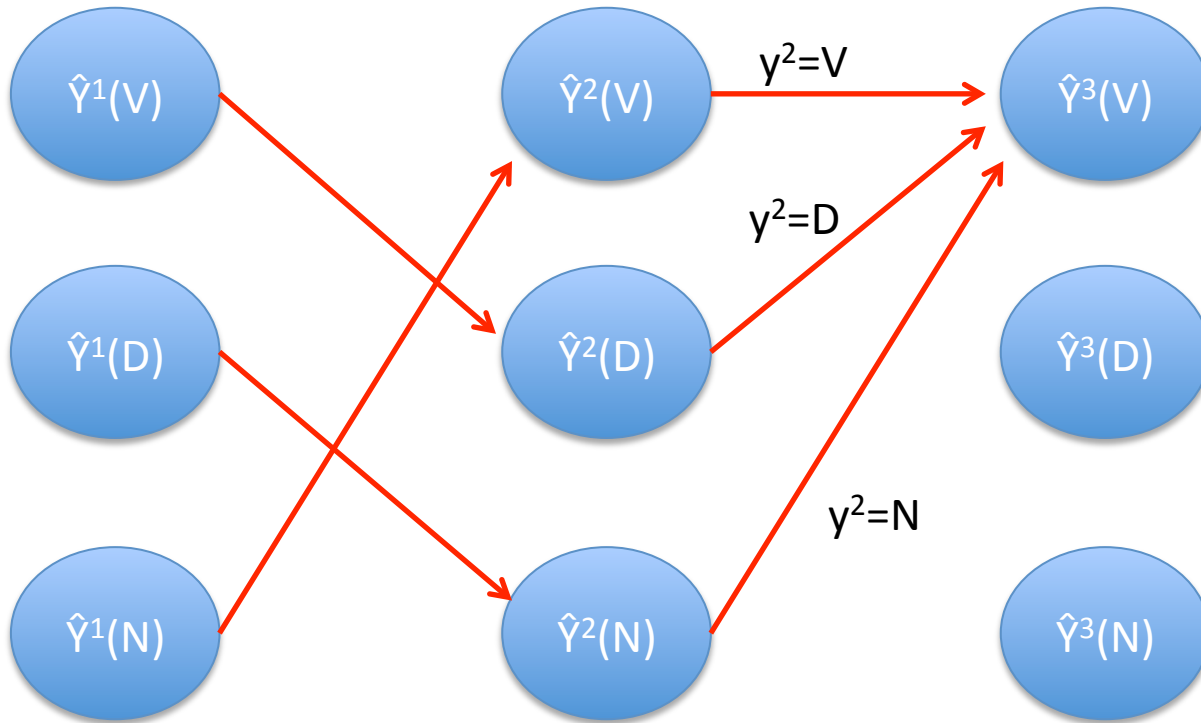
$\hat{Y}^1(T)$ is just T

Ex: $\hat{Y}^2(V) = (N, V)$

Solve: $\hat{Y}^3(V) = \left(\underset{y^{1:2} \{ \hat{Y}^2(T) \}_T}{\operatorname{argmax}} F(y^{1:2}, x^{1:2}) + A_{V, y^2} + O_{V, x^3} \right) \oplus V$

Store each
 $\hat{Y}^1(T)$ & $F(\hat{Y}^1(T), x^1)$

Store each
 $\hat{Y}^2(Z)$ & $F(\hat{Y}^2(Z), x)$



$\hat{Y}^1(Z)$ is just Z

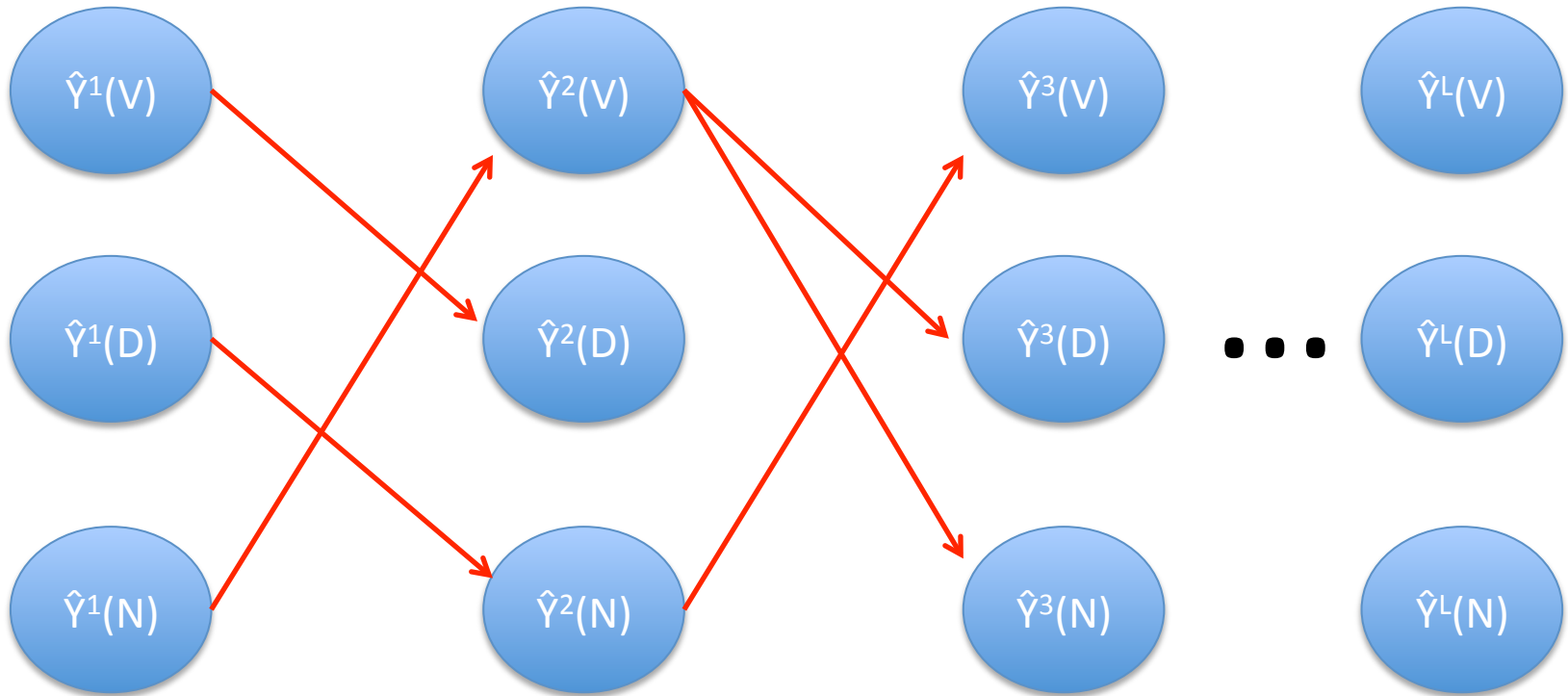
Ex: $\hat{Y}^2(V) = (N, V)$

$$\text{Solve: } \hat{Y}^M(V) = \left(\operatorname{argmax}_{y^{1:M-1} \in \{\hat{Y}^M(T)\}_T} F(y^{1:M-1}, x^{1:M-1}) + A_{V, y^{M-1}} + O_{V, x^M} \right) \oplus V$$

Store each
 $\hat{Y}^1(Z)$ & $F(\hat{Y}^1(Z), x^1)$

Store each
 $\hat{Y}^2(T)$ & $F(\hat{Y}^2(T), x)$

Store each
 $\hat{Y}^3(T)$ & $F(\hat{Y}^3(T), x)$



$\hat{Y}^1(T)$ is just T

Ex: $\hat{Y}^2(V) = (N, V)$

Ex: $\hat{Y}^3(V) = (D, N, V)$

Computing $P(y | x)$

- Viterbi doesn't compute $P(y | x)$
 - Just maximizes the numerator $F(y, x)$

$$P(y | x) = \frac{\exp\{F(y, x)\}}{\sum_{y'} \exp\{F(y', x)\}} \equiv \frac{1}{Z(x)} \exp\{F(y, x)\}$$

- Also need to compute $Z(x)$
 - aka the “Partition Function”

$$Z(x) = \sum_{y'} \exp\{F(y', x)\}$$

Computing Partition Function

- Naive approach is iterate over all y'
 - Exponential time, L^M possible y' !

$$Z(x) = \sum_{y'} \exp\{F(y', x)\} \quad F(y, x) \equiv \sum_{j=1}^M \left(A_{y^j, y^{j-1}} + O_{y^j, x^j} \right)$$

- Notation: $G^j(b, a) = \exp\{A_{b,a} + O_{b,x^j}\}$ Suppressing dependency on x for simpler notation

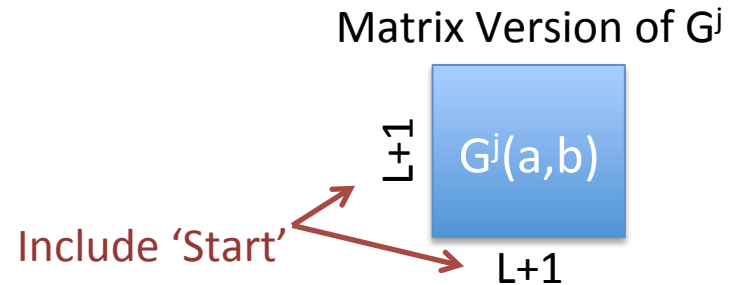
$$P(y | x) = \frac{1}{Z(x)} \prod_{j=1}^M G^j(y^j, y^{j-1})$$

$$Z(x) = \sum_{y'} \prod_{j=1}^M G^j(y'^j, y'^{j-1})$$

Matrix Semiring

$$Z(x) = \sum_{y^1} \prod_{j=1}^M G^j(y^{1j}, y^{1j-1})$$

$$G^j(b, a) = \exp \left\{ A_{b,a} + O_{a,x^j} \right\}$$



$$G^{1:2}(b, a) \equiv \sum_c G^2(b, c) G^1(c, a)$$



Path Counting Interpretation

- Interpretation $G^1(b,a)$
 - $L+1$ start & end locations
 - Weight of path from 'a' to 'b' in step 1



- $G^{1:2}(b,a)$
 - Weight of all paths
 - Start in 'a' beginning of Step 1
 - End in 'b' after Step 2



Computing Partition Function

- Consider Length-1 ($M=1$)

$$Z(x) = \sum_b G^1(b, \text{Start})$$

Sum column 'Start' of G^1 !

- $M=2$

$$Z(x) = \sum_{a,b} G^2(b,a)G^1(a, \text{Start}) = \sum_b G^{1:2}(b, \text{Start})$$

Sum column 'Start' of $G^{1:2}$!

- General M

Sum column 'Start' of $G^{1:M}$!

- Do M $(L+1) \times (L+1)$ matrix computations to compute $G^{1:M}$
- $Z(x) = \text{sum column 'Start' of } G^{1:M}$



Computing Partition Function

- Consider Length-1 ($M=1$)

$$Z(x) = \sum G^1(b, \text{Start})$$

sum column 'Start' of $G^1!$

- $M=2$

Numerical Instability Issues!
(See Course Notes)

(b, Start)

sum column 'Start' of $G^{1:2}!$

- General M

sum column 'Start' of $G^{1:M}!$

- Do M $(L+1) \times (L+1)$ matrix computations to compute $G^{1:M}$
- $Z(x) = \text{sum column 'Start' of } G^{1:M}$

$$G^{1:M} = G^M G^{M-1} \dots G^2 G^1$$

Train via Gradient Descent

- Similar to Logistic Regression

- Gradient Descent on negative log likelihood (log loss)

$$\operatorname{argmin}_{\Theta} \sum_{i=1}^N -\log P(y_i | x_i) = \operatorname{argmin}_{\Theta} \sum_{i=1}^N -F(y_i, x_i) + \log(Z(x_i))$$

Θ often used to denote all parameters of model

Harder to differentiate!

- First term is easy:

- Recall:

$$F(y, x) \equiv \sum_{j=1}^M (A_{y^j, y^{j-1}} + O_{y^j, x^j})$$


$$\partial_{A_{ba}} - F(y, x) = - \sum_{j=1}^M 1_{[(y^j, y^{j-1})=(b,a)]}$$

$$\partial_{O_{az}} - F(y, x) = - \sum_{j=1}^M 1_{[(y^j, x^j)=(a,z)]}$$

Differentiating Log Partition

Lots of Chain Rule & Algebra!

$$\begin{aligned}
 \partial_{A_{ba}} \log(Z(x)) &= \frac{1}{Z(x)} \partial_{A_{ba}} Z(x) = \frac{1}{Z(x)} \partial_{A_{ba}} \sum_{y'} \exp\{F(y', x)\} \\
 &= \frac{1}{Z(x)} \sum_{y'} \partial_{A_{ba}} \exp\{F(y', x)\} \\
 &= \frac{1}{Z(x)} \sum_{y'} \exp\{F(y', x)\} \partial_{A_{ba}} F(y', x) = \sum_{y'} \frac{\exp\{F(y', x)\}}{Z(x)} \partial_{A_{ba}} F(y', x) \\
 &= \sum_{y'} P(y' | x) \partial_{A_{ba}} F(y', x) = \sum_{y'} \left[P(y' | x) \sum_{j=1}^M 1_{[(y'^j, y'^{j-1})=(b,a)]} \right] \\
 &= \sum_{j=1}^M \sum_{y'} P(y' | x) 1_{[(y'^j, y'^{j-1})=(b,a)]} = \sum_{j=1}^M P(y^j = b, y^{j-1} = a | x)
 \end{aligned}$$

Definition
of $P(y' | x)$ 

Forward-Backward!

 Marginalize over all y'

Optimality Condition

$$\operatorname{argmin}_{\Theta} \sum_{i=1}^N -\log P(y_i | x_i) = \operatorname{argmin}_{\Theta} \sum_{i=1}^N -F(y_i, x_i) + \log(Z(x))$$

- Consider one parameter:

$$\partial_{A_{ba}} \sum_{i=1}^N -F(y_i, x_i) = -\sum_{i=1}^N \sum_{j=1}^{M_i} 1_{[(y_i^j, y_i^{j-1})=(b,a)]} \quad \partial_{A_{ba}} \sum_{i=1}^N \log(Z(x)) = \sum_{i=1}^N \sum_{j=1}^{M_i} P(y_i^j = b, y_i^{j-1} = a | x_i)$$

- Optimality condition:

$$\sum_{i=1}^N \sum_{j=1}^{M_i} 1_{[(y_i^j, y_i^{j-1})=(b,a)]} = \sum_{i=1}^N \sum_{j=1}^{M_i} P(y_i^j = b, y_i^{j-1} = a | x_i)$$

- **Frequency counts = Cond. expectation on training data!**
 - Holds for each component of the model
 - Each component is a “log-linear” model and requires gradient desc.

Forward-Backward for CRFs

$$\alpha^1(a) = G^1(a, \text{Start})$$

$$\alpha^j(a) = \sum_{a'} \alpha^{j-1}(a') G^j(a, a')$$

$$\beta^M(b) = 1$$

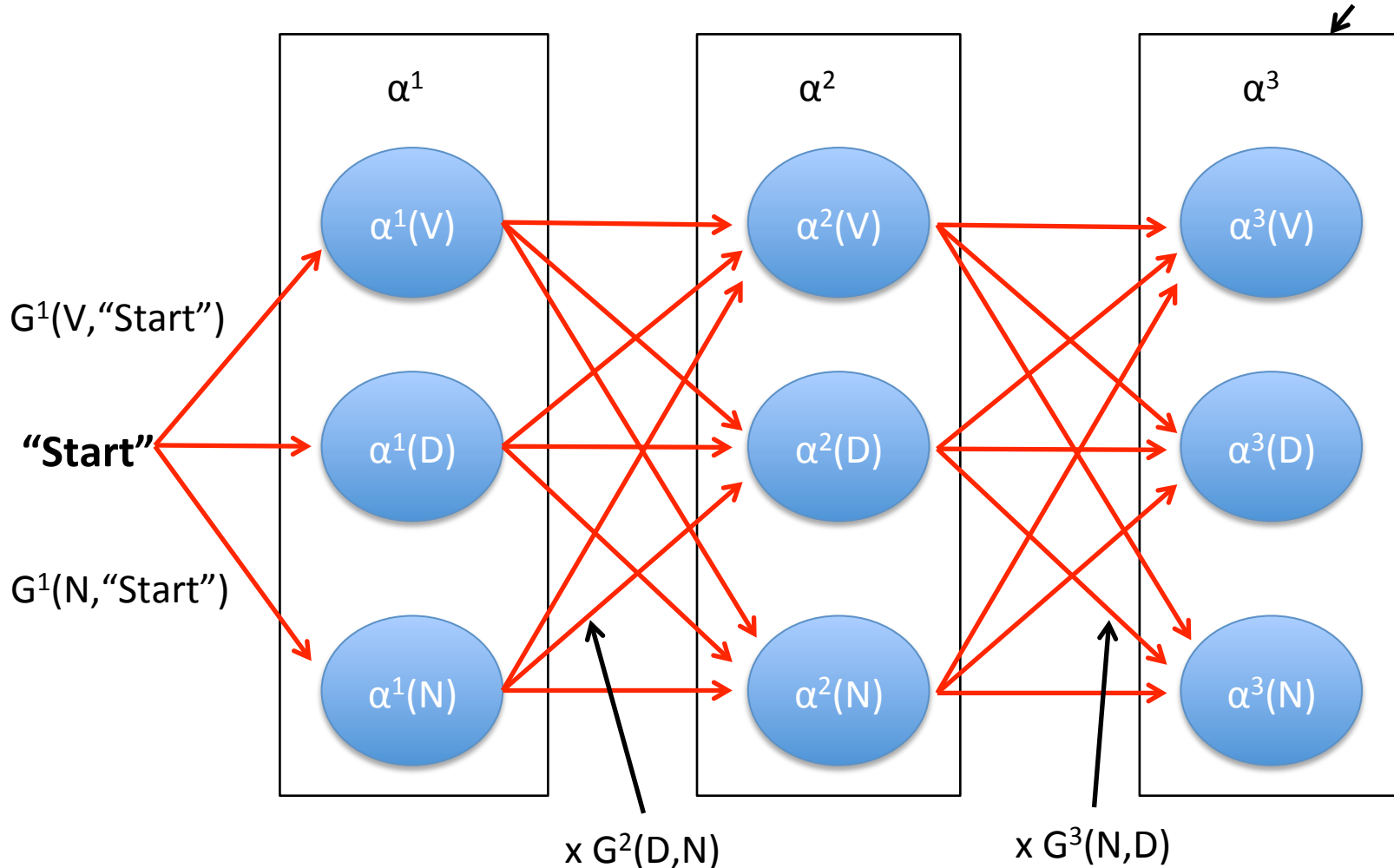
$$\beta^j(b) = \sum_{b'} \beta^{j+1}(b') G^{j+1}(b', b)$$

$$P(y^j = b, y^{j-1} = a \mid x) = \frac{\alpha^{j-1}(a) G^j(b, a) \beta^j(b)}{Z(x)}$$

$$Z(x) = \sum_{y'} \exp\{F(y', x)\} \quad F(y, x) \equiv \sum_{j=1}^M (A_{y^j, y^{j-1}} + O_{y^j, x^j}) \quad G^j(b, a) = \exp\{A_{b, a} + O_{b, x^j}\}$$

Path Interpretation

Total Weight of paths from "Start" to "V" in 3rd step



β just does it backwards

Matrix Formulation

- Use Matrices!
- Fast to compute!
- Easy to implement!



A diagram illustrating a matrix equation. On the left is a vertical purple bar labeled α^2 . To its right is an equals sign. Further right is a large blue square labeled G^2 . To the right of the square is another vertical purple bar labeled α^1 .

$$\alpha^2 = G^2 \alpha^1$$

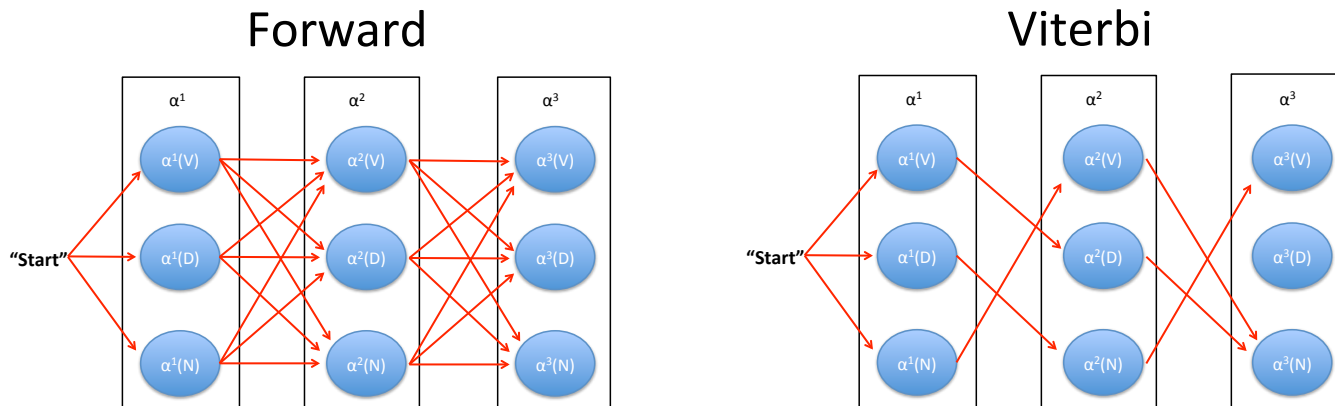


A diagram illustrating a matrix equation. On the left is a vertical red bar labeled β^6 . To its right is an equals sign. Further right is a large blue square labeled $(G^2)^T$. To the right of the square is another vertical red bar labeled β^5 .

$$\beta^6 = (G^2)^T \beta^5$$

Path Interpretation:

Forward-Backward vs Viterbi



- Forward (and Backward) sums over all paths
 - Computes expectation of reaching each state
 - E.g., total (un-normalized) probability of $y^3=\text{Verb}$ over all possible $y^{1:2}$
- Viterbi only keeps the best path
 - Computes best possible path to reaching each state
 - E.g., single highest probability setting of $y^{1:3}$ such that $y^3=\text{Verb}$

Summary: Training CRFs

- Similar optimality condition as HMMs:
 - Match frequency counts of model components!

$$\sum_{i=1}^N \sum_{j=1}^{M_i} 1_{[(y_i^j, y_i^{j-1})=(b,a)]} = \sum_{i=1}^N \sum_{j=1}^{M_i} P(y_i^j = b, y_i^{j-1} = a | x_i)$$

- Except HMMs can just set the model using counts
 - CRFs need to do gradient descent to match counts
- Run Forward-Backward for expectation
 - Just like HMMs as well

Summary: CRFs

- Log-Linear Sequential Model:

$$P(y | x) = \frac{\exp\{F(y, x)\}}{Z(x)}$$
$$F(y, x) \equiv \sum_{j=1}^M (A_{y^j, y^{j-1}} + O_{y^j, x^j})$$
$$Z(x) = \sum_{y'} \exp\{F(y', x)\}$$

- Same #parameters as HMMs
 - Focused on learning $P(y|x)$
 - Prediction via Viterbi
 - Gradient Descent via Forward-Backward

Next Lecture

- More General Formulation of CRFs
 - More concise notation
 - Matches logistic regression notation
 - Matches course notes (later this week)
 - Easier to reason about for implementation
- General Structured Prediction