

Machine Learning & Data Mining

CS/CNS/EE 155

Lecture 10:

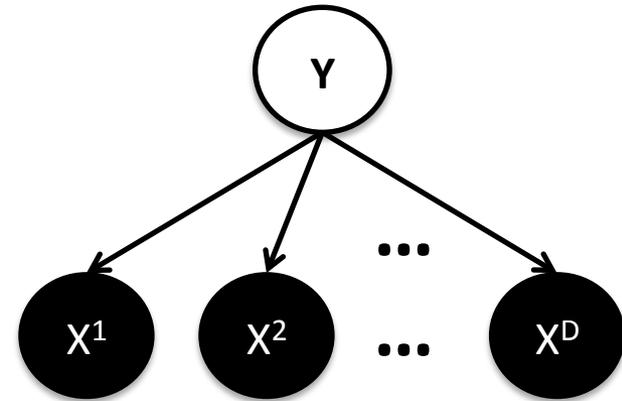
Conditional Random Fields Revisited,
Overview of General Structured Prediction

Today

- Naïve Bayes vs Logistic Regression
 - Detailed Comparison
 - Generalizes Conceptually to HMMs vs CRFs
- Conditional Random Fields Revisited
 - Using Logistic Regression Notation
- Overview of General Structured Prediction

Recall: Naïve Bayes

- Posits a generating model:
 - Single y
 - Multiple x features
 - **Only keep track of:**
 - $P(y), P(x^d | y)$



Graphical Model Diagram

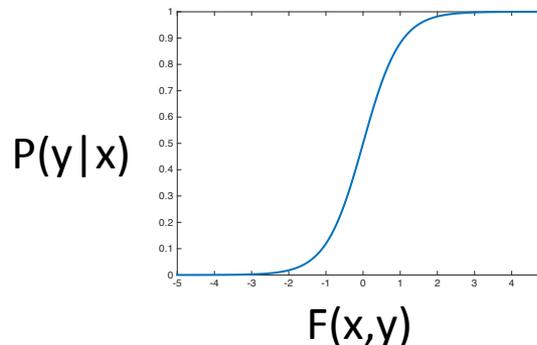
$$P(x, y) = P(x | y)P(y) = P(y) \prod_d P(x^d | y)$$

Each x^d is conditionally independent given y .
“Naïve” independence assumption!

Recall: Logistic Regression

$$P(y|x) = \frac{\exp\{w_y^T x - b_y\}}{\sum_k \exp\{w_k^T x - b_k\}} = \frac{\exp\{F(x, y)\}}{\sum_k \exp\{F(x, k)\}} \quad \begin{array}{l} x \in R^D \\ y \in \{1, 2, \dots, L\} \end{array}$$

- “Log-Linear” assumption
 - Linear scoring function (in exponent)
 - Most common discriminative probabilistic model

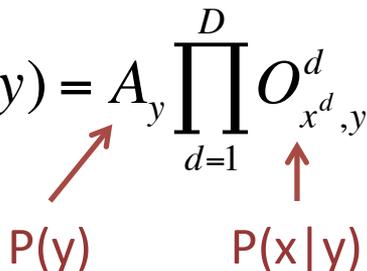


Naïve Bayes vs Logistic Regression

- NB has L parameters for P(y) (i.e., A)
- LR has L parameters for bias b
- NB has L*D parameters for P(x|y) (i.e, O)
- LR has L*D parameters for w
- **Same number of parameters!**

Naïve Bayes

$$P(x, y) = A_y \prod_{d=1}^D O_{x^d, y}^d$$



$P(y)$ $P(x|y)$

Logistic Regression

$$P(y | x) = \frac{e^{w_y^T x - b_y}}{\sum_k e^{w_k^T x - b_k}}$$

$$x \in \{0, 1\}^D$$
$$y \in \{1, 2, \dots, L\}$$

Interpreting Parameters of LR

Logistic Regression

$$\begin{aligned} P(y | x) &= \frac{e^{w_y^T x - b_y}}{\sum_k e^{w_k^T x - b_k}} \\ &\propto \exp\{w_y^T x - b_y\} \\ &= \exp\{-b_y\} \prod_d \exp\{w_y^d x^d\} \\ &= \exp\{A_y\} \prod_d \exp\{O_{x^d, y}^d\} \end{aligned}$$

Rename
Parameters

Naïve Bayes

$$P(x, y) = A_y \prod_{d=1}^D O_{x^d, y}^d$$

$P(y)$ $P(x^d | y)$

Exponent of LR
looks similar to NB!

Cannot ignore
denominator!!!

Modeling $P(y|x)$

Logistic Regression

$$P(y|x) = \frac{\exp\{w_y^T x - b_y\}}{\sum_k \exp\{w_k^T x - b_k\}} = \frac{\exp\left\{\sum_d O_{x^d,y}^d + A_y\right\}}{\sum_k \exp\left\{\sum_d O_{x^d,k}^d + A_k\right\}}$$

Naïve Bayes

$$P(y|x) = \frac{P(x,y)}{P(x)} = \frac{P(x,y)}{\sum_k P(x,k)} = \frac{P(y) \prod_{d=1}^D O_{x^d,y}^d}{\sum_k A_k \prod_{d=1}^D O_{x^d,k}^d}$$

$P(y)$ points to A_y
 $P(x^d|y)$ points to $O_{x^d,y}^d$

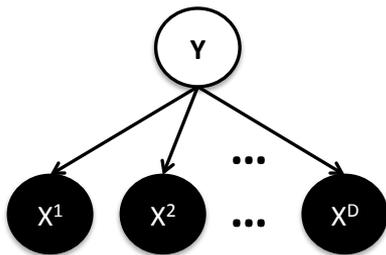
There's no need
for each $A, O \leq 1$

Recall: Training Naïve Bayes

- Maximum Likelihood of Training Set:

$$\begin{aligned}\operatorname{argmax} P(S) &= \operatorname{argmax} \prod_i P(x_i, y_i) & S &= \{(x_i, y_i)\}_{i=1}^N \\ &= \operatorname{argmin} \sum_i -\log P(x_i, y_i)\end{aligned}$$

- Subject to Naïve Bayes assumption on structure of $P(x, y)$



Only need to estimate $P(y)$ and each $P(x^d | y)$!

$$P(x, y) = P(x | y)P(y) = P(y) \prod_d P(x^d | y)$$

Optimality Condition for Naïve Bayes

- **Define:** $P(x | y) = O_{x,y} = \frac{w_{x,y}}{\sum_{x'} w_{x',y}}$

Just a re-parameterization

- **Supervised Training:**

$$\operatorname{argmin} \sum_i [-\log P(x_i | y_i) - \log P(y_i)]$$

$$= \sum_i \left[-\log w_{x_i, y_i} + \log \sum_{x'} w_{x', y_i} \right]$$

training examples (x,y)

$$\partial_{w_{x,y}} = -\frac{N_{x,y}}{w_{x,y}} + \frac{N_y}{\sum_{x'} w_{x',y}} \rightarrow \frac{N_{x,y}}{N_y} = \frac{w_{x,y}}{\sum_{x'} w_{x',y}} \rightarrow P(x | y) = \frac{N_{x,y}}{N_y}$$

**Frequency counts
in training set!**

Recall: Training Logistic Regression

$$\operatorname{argmin} \sum_i -\log P(y_i | x_i) \equiv \sum_i \left[-F(x_i, y_i) + \log \sum_{y'} \exp\{F(x_i, y')\} \right]$$

$$F(x, y) = w_y^T x - b_y = A_y + \sum_d O_{x,y}^d$$

$$P(y | x) = \frac{\exp\{F(x, y)\}}{\sum_{y'} \exp\{F(x, y')\}}$$

Gradient (skipping derivation)

$$\partial_{w_y} = \sum_i \left(-1_{[y_i=y]} + P(y | x_i) \right) \frac{\partial F(x_i, y)}{\partial w_y} = - \sum_i \left(1_{[y_i=y]} - P(y | x_i) \right) \frac{\partial F(x_i, y)}{\partial w_y}$$

Optimality Condition for Logistic Regression

Gradient (skipping derivation)

$$\partial_{w_y} = \sum_i \left(-1_{[y_i=y]} + P(y | x_i) \right) \frac{\partial F(x_i, y)}{\partial w_y} = - \sum_i \left(1_{[y_i=y]} - P(y | x_i) \right) \frac{\partial F(x_i, y)}{\partial w_y}$$

Setting gradient to 0: $0 = - \sum_i \left(1_{[y_i=y]} - P(y | x_i) \right) \frac{\partial F(x_i, y)}{\partial w_y}$

$$\sum_i 1_{[y_i=y]} \frac{\partial F(x_i, y)}{\partial w_y} = \sum_i P(y | x_i) \frac{\partial F(x_i, y)}{\partial w_y}$$

Empirical frequency of y should match predicted frequency!

Comparison of Optimality Conditions

- Naïve Bayes: $P(x | y) = \frac{N_{x,y}}{N_y}$ $P(y) = \frac{N_y}{N}$



Correspond to exactly one model parameter!

- Logistic Regression:

$$\sum_i 1_{[y_i=y]} \frac{\partial F(x_i, y)}{\partial w_y} = \sum_i P(y | x_i) \frac{\partial F(x_i, y)}{\partial w_y}$$


Does **not** correspond to exactly one model parameter!

Comparison of Optimality Conditions

- HMM:
$$P(x | y) = \frac{N_{x,y}}{N_y} \quad P(y | y') = \frac{N_{y',y}}{N_y}$$


Correspond to exactly one model parameter!

- CRF:
$$N_{y',y} \frac{\partial F(x_i, y)}{\partial w_{y,y'}} = \sum_i P(y', y | x_i) \frac{\partial F(x_i, y)}{\partial w_{y,y'}}$$


Does **not** correspond to exactly one model parameter!

Generative	Discriminative
$P(x,y)$ <ul style="list-style-type: none"> Joint model over x and y Cares about everything 	$P(y x)$ (when probabilistic) <ul style="list-style-type: none"> Conditional model Only cares about predicting well
Naïve Bayes, HMMs <ul style="list-style-type: none"> Also Topic Models 	Logistic Regression, CRFs <ul style="list-style-type: none"> also SVM, Least Squares, etc.
Max Likelihood	Max (Conditional) Likelihood <ul style="list-style-type: none"> (=minimize log loss) Can pick any loss based on y Hinge Loss, Squared Loss, etc.
Always Probabilistic	Not Necessarily Probabilistic <ul style="list-style-type: none"> Certainly never joint over $P(x,y)$
Often strong assumptions <ul style="list-style-type: none"> Keeps training tractable 	More flexible assumptions <ul style="list-style-type: none"> Focuses entire model on $P(y x)$
Mismatch between train & predict <ul style="list-style-type: none"> Requires Bayes's rule 	Train to optimize predict goal
Can sample anything	Can only sample y given x
Can handle missing values in x	Cannot handle missing values in x

Recap: Sequence Prediction

- Input: $x = (x^1, \dots, x^M)$
- Predict: $y = (y^1, \dots, y^M)$
 - Each y^i one of L labels.

• $x = \text{“Fish Sleep”}$

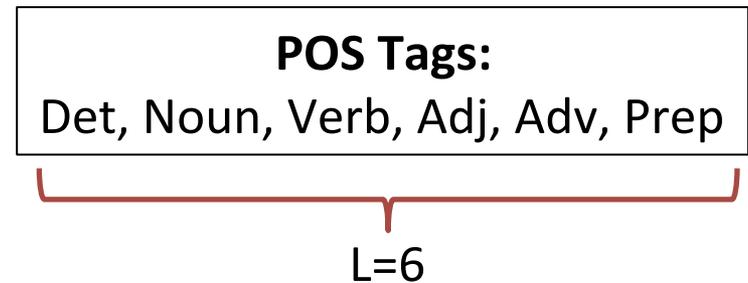
• $y = (N, V)$

• $x = \text{“The Dog Ate My Homework”}$

• $y = (D, N, V, D, N)$

• $x = \text{“The Fox Jumped Over The Fence”}$

• $y = (D, N, V, P, D, N)$



“Log-Linear” 1st Order Sequential Model

$$P(y | x) = \frac{1}{Z(x)} \exp \left\{ \sum_{j=1}^M \left(A_{y^j, y^{j-1}} + O_{y^j, x^j} \right) \right\}$$

$$Z(x) = \sum_{y'} \exp \{ F(y', x) \} \quad \text{aka “Partition Function”}$$

$$F(y, x) \equiv \sum_{j=1}^M \left(A_{y^j, y^{j-1}} + O_{y^j, x^j} \right) \quad \text{Scoring Function}$$

Scoring transitions Scoring input features

$$P(y | x) = \frac{\exp \{ F(y, x) \}}{Z(x)} \quad \log P(y | x) = F(y, x) - \log(Z(x))$$

y^0 = special start state, excluding end state

- $x = \text{"Fish Sleep"}$
- $y = (N, V)$

$$P(y | x) = \frac{1}{Z(x)} \exp \left\{ \sum_{j=1}^M (A_{y^j, y^{j-1}} + O_{y^j, x^j}) \right\}$$

$A_{N,V}$ →

	$A_{N,*}$	$A_{V,*}$
$A_{*,N}$	-2	1
$A_{*,V}$	2	-2
$A_{*,Start}$	1	-1

← $w_{V,Fish}$

	$O_{N,*}$	$O_{V,*}$
$O_{*,Fish}$	2	1
$O_{*,Sleep}$	1	0

$$P(N, V | \text{"Fish Sleep"}) = \frac{1}{Z(x)} \exp \{ A_{N,Start} + O_{N,Fish} + A_{V,N} + O_{V,Sleep} \} = \frac{1}{Z(x)} \exp \{ 4 \}$$

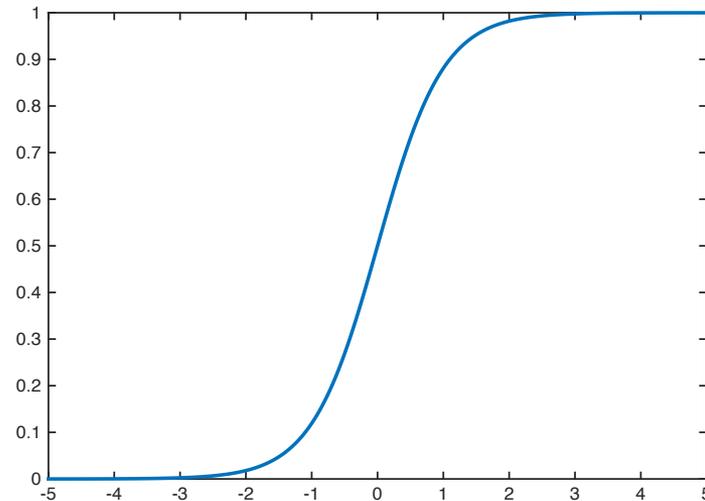
$$Z(x) = \text{Sum} \left(\begin{array}{|c|c|} \hline \mathbf{y} & \mathbf{\exp(F(y,x))} \\ \hline (N,N) & \exp(1+2-2+1) = \exp(2) \\ \hline (N,V) & \exp(1+2+2+0) = \exp(4) \\ \hline (V,N) & \exp(-1+1+2+1) = \exp(3) \\ \hline (V,V) & \exp(-1+1-2+0) = \exp(-2) \\ \hline \end{array} \right)$$

- $x = \text{"Fish Sleep"}$
- $y = (N, V)$

$$P(N, V | \text{"Fish Sleep"}) = \frac{1}{Z(x)} \exp \left\{ A_{N, \text{Start}} + O_{N, \text{Fish}} + A_{V, N} + O_{V, \text{Sleep}} \right\}$$

$P(N, V | \text{"Fish Sleep"})$

*hold other parameters fixed



$$A_{N, \text{Start}} + O_{N, \text{Fish}} + A_{V, N} + O_{V, \text{Sleep}}$$

New Notation

Duplicate word features for each label.

Noun
Class
Features

$$\varphi_1^1(\text{Noun} \mid \text{"Fish Sleep"}) = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\varphi_1^2(\text{Noun} \mid \text{"Fish Sleep"}) = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

Verb
Class
Features

$$\varphi_1^1(\text{Verb} \mid \text{"Fish Sleep"}) = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\varphi_1^2(\text{Verb} \mid \text{"Fish Sleep"}) = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\varphi_1^j(a \mid x) = \begin{bmatrix} 1_{[(a=\text{Noun}) \wedge (x^j = \text{'Fish'})]} \\ 1_{[(a=\text{Noun}) \wedge (x^j = \text{'Sleep'})]} \\ 1_{[(a=\text{Verb}) \wedge (x^j = \text{'Fish'})]} \\ 1_{[(a=\text{Verb}) \wedge (x^j = \text{'Sleep'})]} \end{bmatrix}$$

$$\varphi_1^j(a \mid x) = \begin{bmatrix} 1_{[a=1]} \phi_1(x^j) \\ \vdots \\ 1_{[a=L]} \phi_1(x^j) \end{bmatrix}$$

New Notation

One feature for every transition.

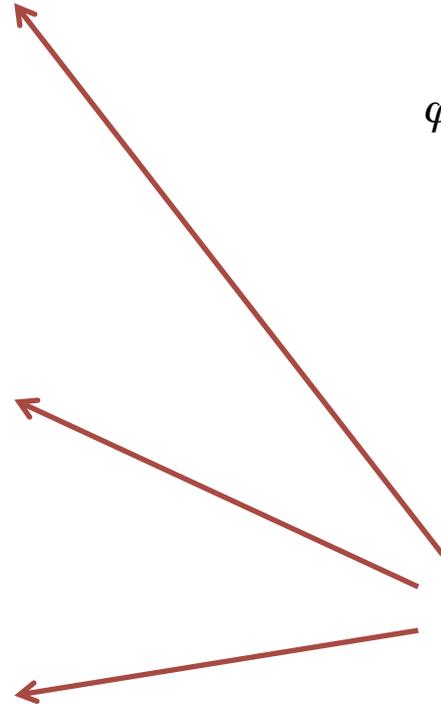
$$\varphi_2(\text{Noun}, \text{Start}) = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\varphi_2(\text{Verb}, \text{Start}) = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\varphi_2(\text{Verb}, \text{Noun}) = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\varphi_1^j(a | x) = \begin{bmatrix} \mathbf{1}_{[(a=\text{Noun}) \wedge (x^j = \text{'Fish'})]} \\ \mathbf{1}_{[(a=\text{Noun}) \wedge (x^j = \text{'Sleep'})]} \\ \mathbf{1}_{[(a=\text{Verb}) \wedge (x^j = \text{'Fish'})]} \\ \mathbf{1}_{[(a=\text{Verb}) \wedge (x^j = \text{'Sleep'})]} \end{bmatrix}$$

$$\varphi_2(a, b) = \begin{bmatrix} \mathbf{1}_{[(a=\text{Noun}) \wedge (b=\text{Start})]} \\ \mathbf{1}_{[(a=\text{Noun}) \wedge (b=\text{Noun})]} \\ \mathbf{1}_{[(a=\text{Noun}) \wedge (b=\text{Verb})]} \\ \mathbf{1}_{[(a=\text{Verb}) \wedge (b=\text{Start})]} \\ \mathbf{1}_{[(a=\text{Verb}) \wedge (b=\text{Noun})]} \\ \mathbf{1}_{[(a=\text{Verb}) \wedge (b=\text{Verb})]} \end{bmatrix}$$



New Notation

$$F(y, x) \equiv \sum_{j=1}^M \left(A_{y^j, y^{j-1}} + O_{y^j, x^j} \right)$$

Scoring transitions
Scoring input features

Old Scoring Function

$$F(y, x) \equiv \sum_{j=1}^M \left[w^T \varphi^j(y^j, y^{j-1} | x) \right]$$

Stacked Weight Vector
Stacked Feature Vector

New Scoring Function

$w = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}$

$\varphi^j(a, a' | x) = \begin{bmatrix} \varphi_1^j(a | x) \\ \varphi_2^j(a, a') \end{bmatrix}$

$$\varphi_1^j(a | x) = \begin{bmatrix} \mathbb{1}[(a=Noun) \wedge (x^j='Fish')] \\ \mathbb{1}[(a=Noun) \wedge (x^j='Sleep')] \\ \mathbb{1}[(a=Verb) \wedge (x^j='Fish')] \\ \mathbb{1}[(a=Verb) \wedge (x^j='Sleep')] \end{bmatrix}$$

$$\varphi_2^j(a, a') = \begin{bmatrix} \mathbb{1}[(a=Noun) \wedge (a'='Start')] \\ \mathbb{1}[(a=Noun) \wedge (a'='Noun')] \\ \mathbb{1}[(a=Noun) \wedge (a'='Verb')] \\ \mathbb{1}[(a=Verb) \wedge (a'='Start')] \\ \mathbb{1}[(a=Verb) \wedge (a'='Noun')] \\ \mathbb{1}[(a=Verb) \wedge (a'='Verb')] \end{bmatrix}$$

$$F(y, x) \equiv \sum_{j=1}^M [w^T \varphi^j(y^j, y^{j-1} | x)]$$

$$w = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}$$

$$\varphi^j(a, a' | x) = \begin{bmatrix} \varphi_1^j(a | x) \\ \varphi_2^j(a, a') \end{bmatrix}$$

Old Notation:

	$O_{N,*}$	$O_{V,*}$
$O_{*,Fish}$	2	1
$O_{*,Sleep}$	1	0

$$w_1 = \begin{bmatrix} 2 \\ 1 \\ 1 \\ 0 \end{bmatrix} \quad \varphi_1^j(a | x) = \begin{bmatrix} 1_{[(a=Noun) \wedge (x^j='Fish')]} \\ 1_{[(a=Noun) \wedge (x^j='Sleep')]} \\ 1_{[(a=Verb) \wedge (x^j='Fish')]} \\ 1_{[(a=Verb) \wedge (x^j='Sleep')]} \end{bmatrix}$$

Old Notation:

	$A_{N,*}$	$A_{V,*}$
$A_{*,N}$	-2	1
$A_{*,V}$	2	-2
$A_{*,Start}$	1	-1

$$w_2 = \begin{bmatrix} 1 \\ -2 \\ 2 \\ -1 \\ 1 \\ -2 \end{bmatrix}$$

$$\varphi_2(a, a') = \begin{bmatrix} 1_{[(a=Noun) \wedge (a'='Start')]} \\ 1_{[(a=Noun) \wedge (a'='Noun')]} \\ 1_{[(a=Noun) \wedge (a'='Verb')]} \\ 1_{[(a=Verb) \wedge (a'='Start')]} \\ 1_{[(a=Verb) \wedge (a'='Noun')]} \\ 1_{[(a=Verb) \wedge (a'='Verb')]} \end{bmatrix}$$

Why New Notation?

- Easier to reason about:
 - Computing Predictions
 - Computing Gradients
 - Extensions (just generalize ϕ)

$$\varphi_1^j(a | x) = \begin{bmatrix} \mathbf{1}_{[(a=Noun) \wedge (x^j = 'Fish')]} \\ \mathbf{1}_{[(a=Noun) \wedge (x^j = 'Sleep')]} \\ \mathbf{1}_{[(a=Verb) \wedge (x^j = 'Fish')]} \\ \mathbf{1}_{[(a=Verb) \wedge (x^j = 'Sleep')]} \end{bmatrix}$$

$$F(y, x) \equiv \sum_{j=1}^M [w^T \varphi^j(y^j, y^{j-1} | x)]$$

$$w = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} \quad \varphi^j(a, b | x) = \begin{bmatrix} \varphi_1^j(a | x) \\ \varphi_2(a, b) \end{bmatrix}$$


$$\varphi_2(a, b) = \begin{bmatrix} \mathbf{1}_{[(a=Noun) \wedge (b=Start)]} \\ \mathbf{1}_{[(a=Noun) \wedge (b=Noun)]} \\ \mathbf{1}_{[(a=Noun) \wedge (b=Verb)]} \\ \mathbf{1}_{[(a=Verb) \wedge (b=Start)]} \\ \mathbf{1}_{[(a=Verb) \wedge (b=Noun)]} \\ \mathbf{1}_{[(a=Verb) \wedge (b=Verb)]} \end{bmatrix}$$

Conditional Random Fields

$$P(y | x) = \frac{1}{Z(x)} \exp\{F(y, x)\}$$

$$Z(x) = \sum_{y'} \exp\{F(y', x)\}$$

$$F(y, x) \equiv \sum_{j=1}^M [w^T \varphi^j(y^j, y^{j-1} | x)]$$

$$w = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} \quad \varphi^j(a, b | x) = \begin{bmatrix} \varphi_1^j(a | x) \\ \varphi_2(a, b) \end{bmatrix}$$

$$\varphi_1^j(a | x) = \begin{bmatrix} \mathbf{1}_{[(a=Noun) \wedge (x^j = 'Fish')]} \\ \mathbf{1}_{[(a=Noun) \wedge (x^j = 'Sleep')]} \\ \mathbf{1}_{[(a=Verb) \wedge (x^j = 'Fish')]} \\ \mathbf{1}_{[(a=Verb) \wedge (x^j = 'Sleep')]} \end{bmatrix}$$

$$\varphi_2(a, b) = \begin{bmatrix} \mathbf{1}_{[(a=Noun) \wedge (b=Start)]} \\ \mathbf{1}_{[(a=Noun) \wedge (b=Noun)]} \\ \mathbf{1}_{[(a=Noun) \wedge (b=Verb)]} \\ \mathbf{1}_{[(a=Verb) \wedge (b=Start)]} \\ \mathbf{1}_{[(a=Verb) \wedge (b=Noun)]} \\ \mathbf{1}_{[(a=Verb) \wedge (b=Verb)]} \end{bmatrix}$$

$x = \text{"Fish Sleep"}$

$y = (N, V)$

$$w_1 = \begin{bmatrix} 2 \\ 1 \\ 1 \\ 0 \end{bmatrix} \quad \varphi_1^j(a | x) = \begin{bmatrix} 1_{[(a=Noun) \wedge (x^j = 'Fish')]} \\ 1_{[(a=Noun) \wedge (x^j = 'Sleep')]} \\ 1_{[(a=Verb) \wedge (x^j = 'Fish')]} \\ 1_{[(a=Verb) \wedge (x^j = 'Sleep')]} \end{bmatrix}$$

$$w_2 = \begin{bmatrix} 1 \\ -2 \\ 2 \\ -1 \\ 1 \\ -2 \end{bmatrix}$$

$$\varphi_2^j(a, a') = \begin{bmatrix} 1_{[(a=Noun) \wedge (a' = Start)]} \\ 1_{[(a=Noun) \wedge (a' = Noun)]} \\ 1_{[(a=Noun) \wedge (a' = Verb)]} \\ 1_{[(a=Verb) \wedge (a' = Start)]} \\ 1_{[(a=Verb) \wedge (a' = Noun)]} \\ 1_{[(a=Verb) \wedge (a' = Verb)]} \end{bmatrix}$$

$$P(N, V | x = \text{"Fish Sleep"}) = \frac{1}{Z(x)} \exp\{w_1^T \varphi_1^1(N, x) + w_2^T \varphi_2(N, Start) + w_1^T \varphi_1^2(V, x) + w_2^T \varphi_2(V, N)\}$$

$$= \frac{1}{Z(x)} \exp\{w_{1,1} + w_{2,1} + w_{1,4} + w_{2,5}\} = \frac{1}{Z(x)} \exp\{2 + 1 + 0 + 1\} = \frac{1}{Z(x)} \exp\{4\}$$

$Z(x) = \text{Sum}$ (

y	$\exp(F(y,x))$
(N,N)	$\exp(2+1+1-2) = \exp(2)$
(N,V)	$\exp(2+1+0+1) = \exp(4)$
(V,N)	$\exp(1-1+1+2) = \exp(3)$
(V,V)	$\exp(1-1+0-2) = \exp(-2)$

)

Summary of New Notation

- Generic Logistic Model Notation:

$$P(y | x) = \frac{1}{Z(x)} \exp\{F(y, x)\}$$

$$Z(x) = \sum_{y'} \exp\{F(y', x)\} \quad F(y, x) \equiv \sum_{j=1}^M [w^T \varphi^j(y^j, y^{j-1} | x)]$$

- Define feature function:
 - Linear model in feature representation
 - Applies to both CRFs and basic LR

Computing Predictions (Viterbi)

$$\operatorname{argmax}_y P(y | x) = \operatorname{argmax}_y F(y, x) \quad F(y^{1:k}, x) \equiv \sum_{j=1}^k [w^T \varphi^j(y^j, y^{j-1} | x)]$$

Maintain length-k
prefix solutions

$$\hat{Y}^k(T) = \left(\operatorname{argmax}_{y^{1:k-1}} F(y^{1:k-1} \oplus T, x) \right) \oplus T$$

Recursively solve for
length-(k+1) solutions

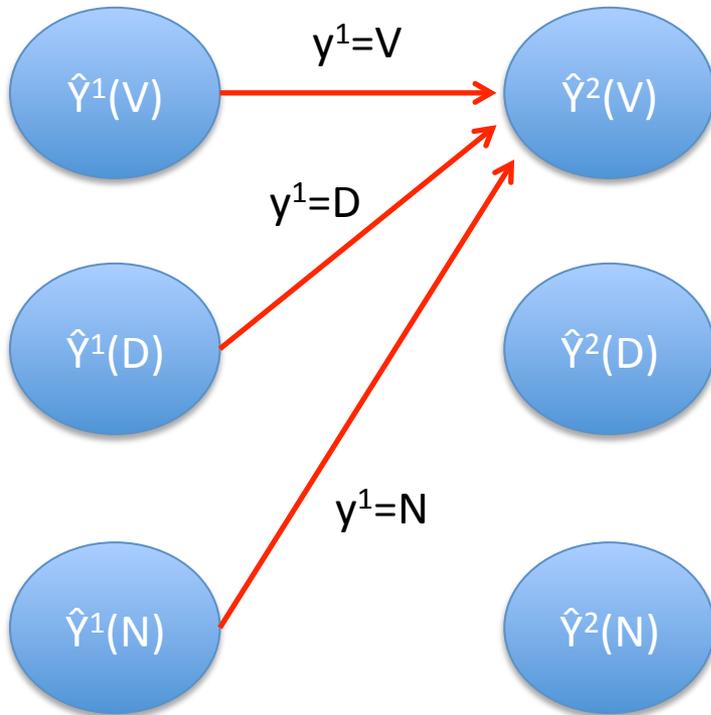
$$\begin{aligned} \hat{Y}^{k+1}(T) &= \left(\operatorname{argmax}_{y^{1:k} \in \{\hat{Y}^k(T)\}_T} F(y^{1:k} \oplus T, x) \right) \oplus T \\ &= \left(\operatorname{argmax}_{y^{1:k} \in \{\hat{Y}^k(T)\}_T} F(y^{1:k}, x) + w^T \varphi^{k+1}(T, y^k, x) \right) \oplus T \end{aligned}$$

Predict via best
length-M solution

$$\operatorname{argmax}_y F(y, x) = \operatorname{argmax}_{y \in \{\hat{Y}^M(T)\}_T} F(y, x)$$

Solve:
$$\hat{Y}^2(V) = \left(\underset{y^1 \in \{\hat{Y}^1(T)\}_T}{\operatorname{argmax}} F(y^1, x) + w^T \varphi^2(V, y^1 | x) \right) \oplus V$$

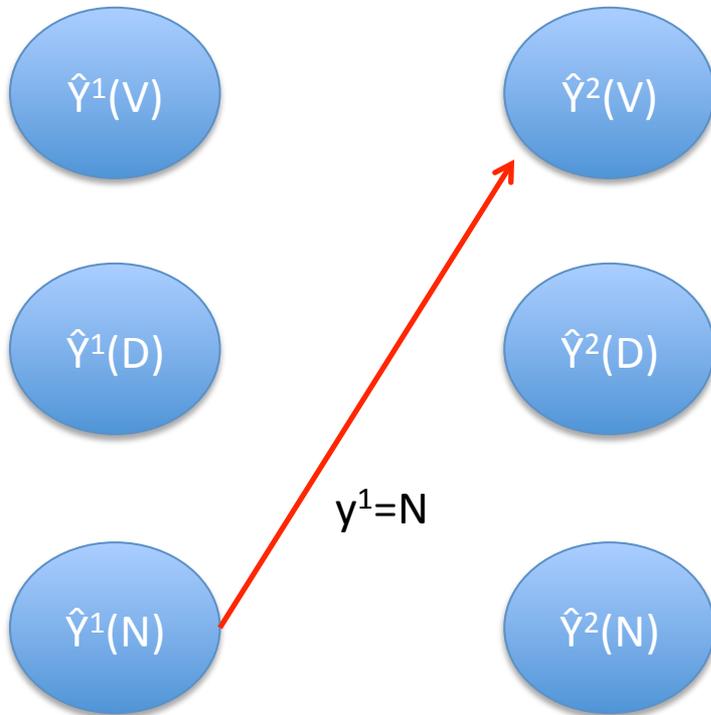
Store each $\hat{Y}^1(T)$ & $F(\hat{Y}^1(T), x)$



$\hat{Y}^1(T)$ is just T

Solve:
$$\hat{Y}^2(V) = \left(\operatorname{argmax}_{y^1 \in \{\hat{Y}^1(T)\}_T} F(y^1, x) + w^T \varphi^2(V, y^1 | x) \right) \oplus V$$

Store each $\hat{Y}^1(T)$ & $F(\hat{Y}^1(T), x)$



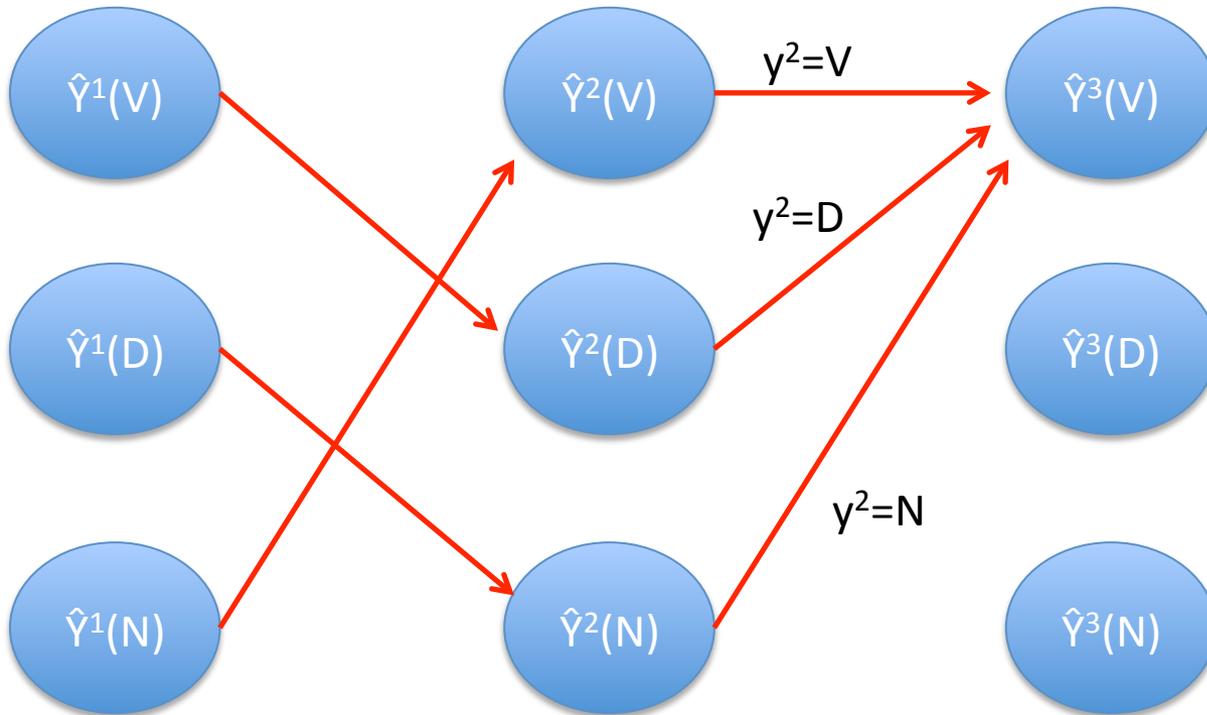
$\hat{Y}^1(T)$ is just T

Ex: $\hat{Y}^2(V) = (N, V)$

Solve:
$$\hat{Y}^3(V) = \left(\operatorname{argmax}_{y^{1:2} \in \{\hat{Y}^2(T)\}_T} F(y^{1:2}, x) + w^T \varphi^j(V, y^2 | x) \right) \oplus V$$

Store each $\hat{Y}^1(T)$ & $F(\hat{Y}^1(T), x)$

Store each $\hat{Y}^2(Z)$ & $F(\hat{Y}^2(Z), x)$



$\hat{Y}^1(Z)$ is just Z

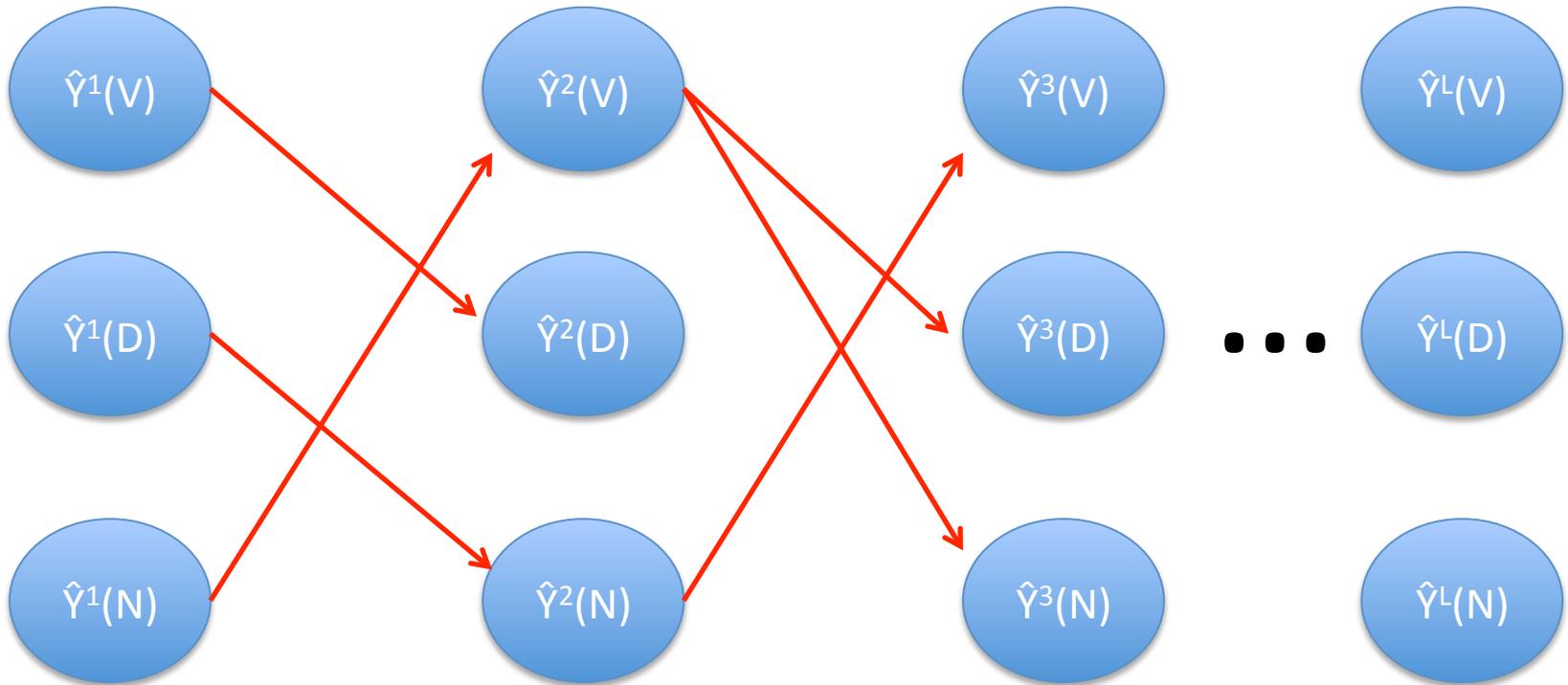
Ex: $\hat{Y}^2(V) = (N, V)$

$$\text{Solve: } \hat{Y}^M(V) = \left(\operatorname{argmax}_{y^{1:M-1} \in \{\hat{Y}^{M-1}(T)\}_T} F(y^{1:M-1}, x) + w^T \varphi^M(V, y^{M-1} | x) \right) \oplus V$$

Store each
 $\hat{Y}^1(Z)$ & $F(\hat{Y}^1(Z), x)$

Store each
 $\hat{Y}^2(T)$ & $F(\hat{Y}^2(T), x)$

Store each
 $\hat{Y}^3(T)$ & $F(\hat{Y}^3(T), x)$



$\hat{Y}^1(T)$ is just T

Ex: $\hat{Y}^2(V) = (N, V)$

Ex: $\hat{Y}^3(V) = (D, N, V)$

$$\text{Solve: } \hat{Y}^M(V) = \left(\operatorname{argmax}_{y^{1:M-1} \in \{\hat{Y}^{M-1}(T)\}_T} F(y^{1:M-1}, x) + w^T \varphi^M(V, y^{M-1} | x) \right) \oplus V$$

Store each
 $\hat{Y}^1(Z)$ & $F(\hat{Y}^1(Z), x)$

Store each
 $\hat{Y}^2(T)$ & $F(\hat{Y}^2(T), x)$

Store each
 $\hat{Y}^3(T)$ & $F(\hat{Y}^3(T), x)$

Decomposes additively by
 pairwise feature vector:
 $\phi^j(a, b | x)$

Easier to keep track of!

$\hat{Y}^1(T)$ is just T

Ex: $\hat{Y}^2(V) = (N, V)$

Ex: $\hat{Y}^3(V) = (D, N, V)$

Computing Conditional Probabilities

$$P(y | x) = \frac{1}{Z(x)} \exp\{F(y, x)\} = \frac{1}{Z(x)} \exp\left\{\sum_{j=1}^M w^T \varphi^j(y^j, y^{j-1} | x)\right\}$$

$$Z(x) = \sum_{y'} \exp\{F(y', x)\}$$

Matrix Notation: $\longrightarrow G^j(b, a) = \exp\{w^T \varphi^j(b, a | x)\}$

Challenges:

- Compute $Z(x)$ efficiently
- Numerical instability

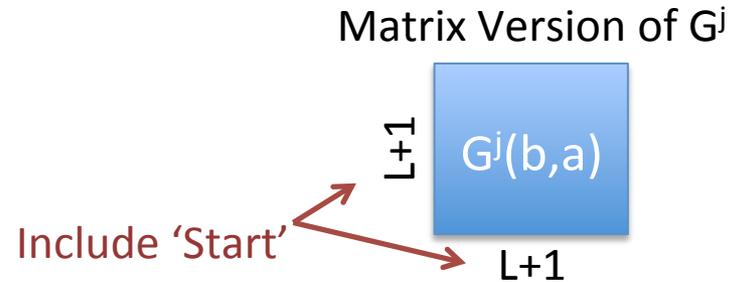
$$P(y | x) = \frac{1}{Z(x)} \prod_{j=1}^M G^j(y^j, y^{j-1})$$

$$Z(x) = \sum_{y'} \prod_{j=1}^M G^j(y'^j, y'^{j-1})$$

Matrix Semiring

$$Z(x) = \sum_{y'} \prod_{j=1}^M G^j(y'^j, y'^{j-1})$$

$$G^j(b, a) = \exp\{w^T \varphi^j(b, a | x)\}$$



$$G^{1:2}(b, a) \equiv \sum_c G^2(b, c) G^1(c, a)$$



See course notes.

Computing Partition Function

- Consider Length-1 ($M=1$)

$$Z(x) = \sum_a G^1(a, Start)$$

Sum column 'Start' of G^1 !

- $M=2$

$$Z(x) = \sum_{a,b} G^2(b,a)G^1(a, Start) = \sum_b G^{1:2}(b, Start)$$

Sum column 'Start' of $G^{1:2}$!

- General M

Sum column 'Start' of $G^{1:M}$!

- Do M matrix computations to compute $G^{1:M}$
- $Z(x) = \text{sum column 'Start' of } G^{1:M}$



See course notes for more efficient approach.

Dealing w/ Numerical Instability

- Previous slide suffers from numerical instability
 - $G^{1:k}$ can easily overflow and/or underflow

Numerical Stability va Scaling:

$$\hat{G}^{1:j} = \frac{1}{C^j} \left(G^j \hat{G}^{1:j-1} \right)$$

$$G^{1:M} = \hat{G}^{1:M} \prod_{j=1}^M C^j$$

Example Scaling Factor:

$$C^j = \sum_{a,b} \left[G^j \hat{G}^{1:j-1} \right]_{ba}$$

$$\log(Z(x)) = \log \left(\sum_a G_{a,Start}^{1:M} \right) = \log \left(\sum_a \hat{G}_{a,Start}^{1:M} \right) + \sum_{j=1}^M \log(C^j)$$

$$\log(P(y|x)) = F(y,x) - \log(Z(x))$$

Use log probs instead!

Training

(Stochastic) Gradient Descent

- Minimize log loss of training data:

$$\operatorname{argmin}_w \sum_{i=1}^N -\log P(y_i | x_i) = \operatorname{argmin}_w \sum_{i=1}^N -F(y_i, x_i) + \log(Z(x_i))$$

$$\partial_w -F(y, x) = -\sum_{j=1}^M \varphi^j(y^j, y^{j-1} | x)$$

$$\partial_w \log(Z(x)) = \sum_{j=1}^M \sum_{a,b} P(y^j = b, y^{j-1} = a | x) \varphi^j(b, a | x)$$

See course notes.

$$S = \{(x_i, y_i)\}_{i=1}^N$$

Optimality Condition

$$\operatorname{argmin}_{\Theta} \sum_{i=1}^N -\log P(y_i | x_i) = \operatorname{argmin}_{\Theta} \sum_{i=1}^N -F(y_i, x_i) + \log(Z(x_i))$$

- Optimality condition:

$$\sum_{i=1}^N \sum_{j=1}^{M_i} \varphi^j(y_i^j, y_i^{j-1} | x_i) = \sum_{i=1}^N \sum_{j=1}^{M_i} \sum_{a,b} P(y^j = b, y^{j-1} = a | x_i) \varphi^j(b, a | x_i)$$

- **Frequency counts = Cond. expectation on training data!**

– If each feature is disjoint, then above equality holds for each (a,b):

$$\sum_{i=1}^N \sum_{j=1}^{M_i} 1_{[(y_i^j=b) \wedge (y_i^{j-1}=a)]} \varphi^j(b, a | x_i) = \sum_{i=1}^N \sum_{j=1}^{M_i} P(y^j = b, y^{j-1} = a | x_i) \varphi^j(b, a | x_i)$$

See course notes.

$$S = \{(x_i, y_i)\}_{i=1}^N$$

Computing $P(y^j=b, y^{j-1}=a | x)$ (Forward-Backward)

$$\partial_w \log(Z(x)) = \sum_{j=1}^M \sum_{a,b} P(y^j = b, y^{j-1} = a | x) \varphi^j(b, a | x)$$

$$P(y^j = b, y^{j-1} = a | x) = \sum_{y^{1:j-2}} \sum_{y^{j+1:M}} P(y^{1:j-2} \oplus (a, b) \oplus y^{j+1:M} | x)$$

Forward Computes
1st Sum Efficiently

Backward Computes
2nd Sum Efficiently

Forward-Backward for CRFs

$$\alpha^1(a) = G^1(a, \text{Start})$$

$$\alpha^j(a) = \sum_{a'} \alpha^{j-1}(a') G^j(a, a')$$

$$\beta^M(b) = 1$$

$$\beta^j(b) = \sum_{b'} \beta^{j+1}(b') G^{j+1}(b', b)$$

$$P(y^j = b, y^{j-1} = a \mid x) = \frac{\alpha^{j-1}(a) G^j(b, a) \beta^j(b)}{Z(x)}$$

$$Z(x) = \sum_{y'} \exp\{F(y', x)\}$$

$$G^j(b, a) = \exp\{w^T \varphi^j(b, a \mid x)\}$$

See course notes.

Dealing w/ Numerical Instability

- Numerical instability: α^j & β^j vectors can blow up
- Observation:

$$P(y^j = b, y^{j-1} = a | x) = \frac{\alpha^{j-1}(a)G^j(b, a)\beta^j(b)}{Z(x)} = \frac{\alpha^{j-1}(a)G^j(b, a)\beta^j(b)}{\sum_{a', b'} \alpha^{j-1}(a')G^j(b', a')\beta^j(b')}$$

- New α^j & β^j vectors:

$$\hat{\alpha}^j(a) = \frac{1}{C_\alpha^j} \sum_b \hat{\alpha}^{j-1}(b)G^j(a, b) \quad \hat{\beta}^j(b) = \frac{1}{C_\beta^j} \sum_a \hat{\beta}^{j+1}(a)G^j(a, b)$$

$$C_\alpha^j = \sum_{a, b} \hat{\alpha}^{j-1}(b)G^j(a, b) \quad C_\beta^j = \sum_{a, b} \hat{\beta}^{j+1}(a)G^j(a, b)$$

See course notes.

Recap: Conditional Random Fields

- “Log-Linear” 1st order sequence models
 - Can compute conditional probabilities $P(y|x)$
- Pairwise feature maps $\phi^j(b,a|x)$
 - Arbitrary features that depend on pairs of labels.
- Train via minimizing neg log likelihood
- Dynamic programming to train and predict

General Structured Prediction

More Elaborate Scoring Functions

- Structure encoded by linear scoring function:

$$F(y, x)$$

- 2nd Order Sequential Model:

$$F(y, x) \equiv \sum_{j=1}^M \left[w^T \varphi^j(y^j, y^{j-1}, y^{j-2} | x) \right]$$

- Classification Model:

$$F(y, x) \equiv w^T \varphi(y | x)$$

- Efficient Prediction:

$$\operatorname{argmax}_y F(y, x)$$

More Elaborate Scoring Functions

- Structure encoded by linear scoring function:

$$F(y, x)$$

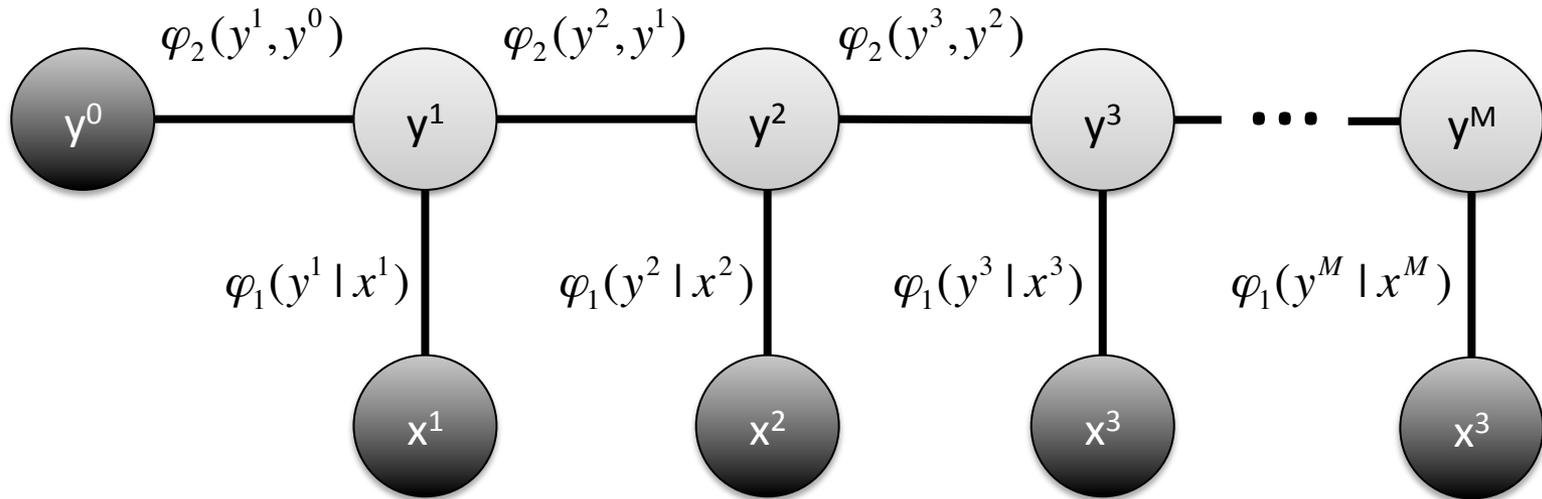
Remainder of Lecture:
Tour of Structured Prediction Models
Some Might be Interesting to You...

- Efficient Prediction:

$$\operatorname{argmax}_y F(y, x)$$

Graphical Models

$$\varphi^j(a, b | x) = \begin{bmatrix} \varphi_1(a | x^j) \\ \varphi_2(a, b) \end{bmatrix}$$



Graph structure encodes structural dependencies between y^j !

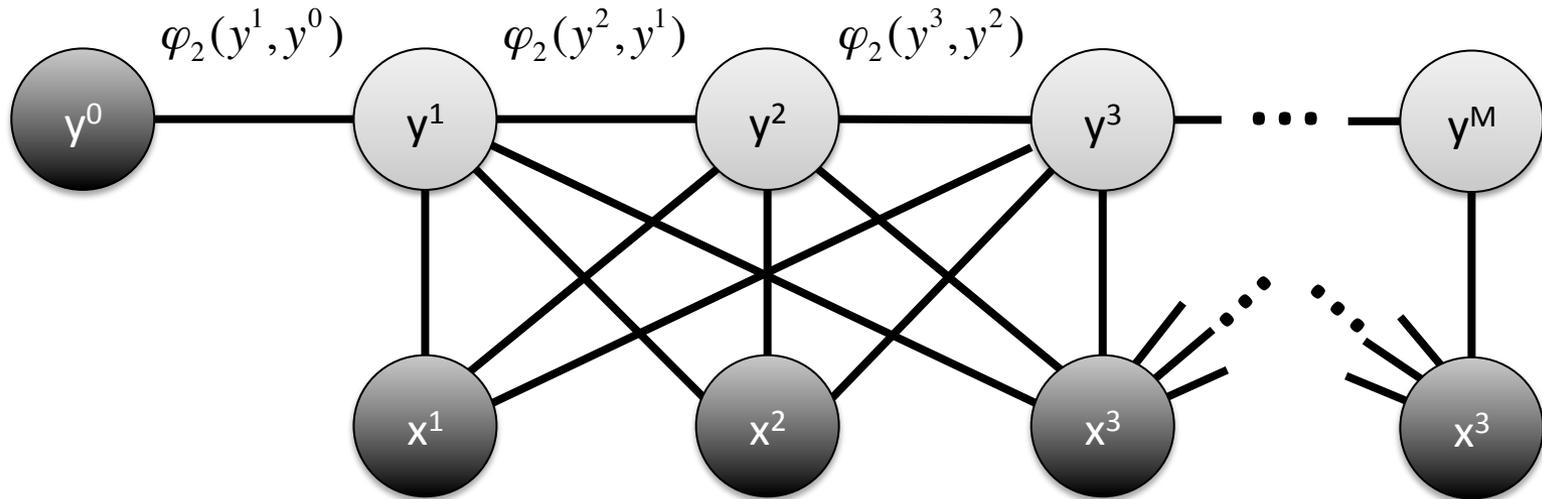
<https://piazza.com/cornell/fall2013/btry6790cs6782/resources>

<http://www.cs.cmu.edu/~guystrin/Class/10708/>

<https://www.coursera.org/course/pgm>

Graphical Models

$$\varphi^j(a,b|x) = \begin{bmatrix} \varphi_1^j(a|x) \\ \varphi_2(a,b) \end{bmatrix}$$



Graph structure encodes structural dependencies between y^j !

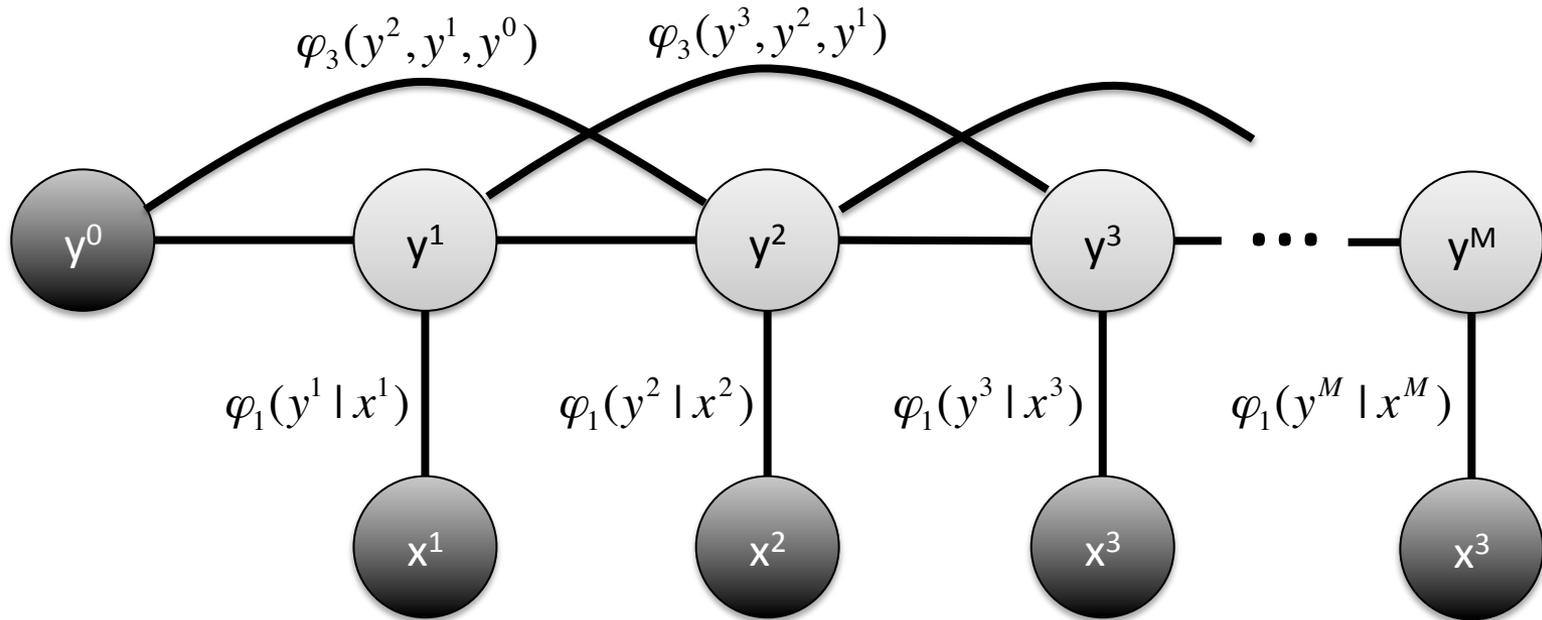
<https://piazza.com/cornell/fall2013/btry6790cs6782/resources>

<http://www.cs.cmu.edu/~gustrin/Class/10708/>

<https://www.coursera.org/course/pgm>

Graphical Models

$$\varphi^j(a,b,c|x) = \begin{bmatrix} \varphi_1(a|x^j) \\ \varphi_3(a,b,c) \end{bmatrix}$$



Graph structure encodes structural dependencies between y^j !

Features depend on cliques in graphical model representation.

<https://piazzacom/cornell/fall2013/btry6790cs6782/resources>

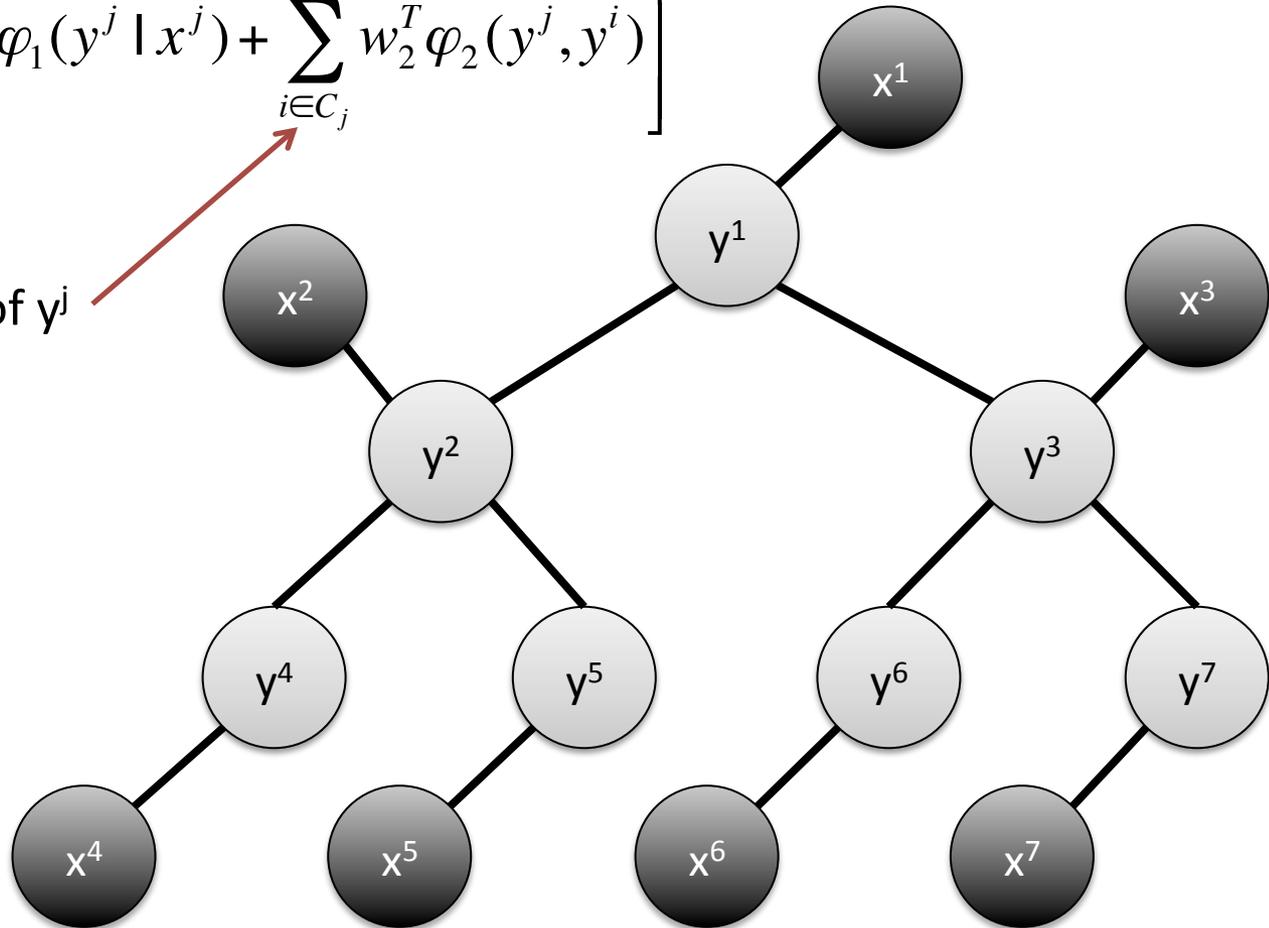
<http://www.cs.cmu.edu/~guyton/Class/10708/>

<https://www.coursera.org/course/pgm>

Tree Structured Models

$$F(y, x) \equiv \sum_{j=1}^M \left[w_1^T \varphi_1(y^j | x^j) + \sum_{i \in C_j} w_2^T \varphi_2(y^j, y^i) \right]$$

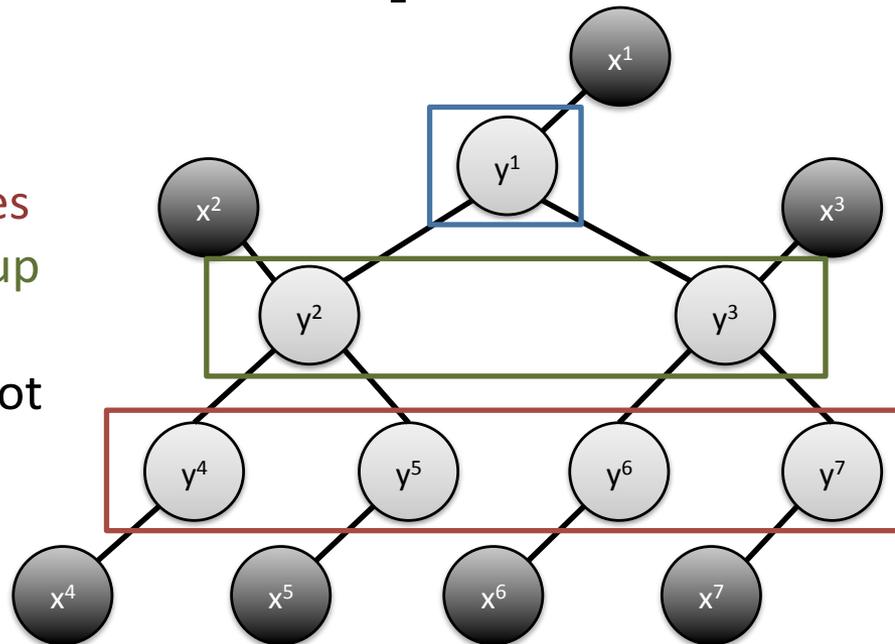
Child nodes of y^j



Prediction via Dynamic Programming

$$F(y, x) \equiv \sum_{j=1}^M \left[w_1^T \varphi_1(y^j | x^j) + \sum_{i \in C_j} w_2^T \varphi_2(y^j, y^i) \right]$$

1. Solve partial solutions of Leaves
2. Solve partial sol. of next level up
3. Repeat Step 2 until Root
4. Pick best partial solution of Root



*Max-Product Algorithm for Tree Graphical Models

*Viterbi = Max-Product for Linear Chain Graphical Models

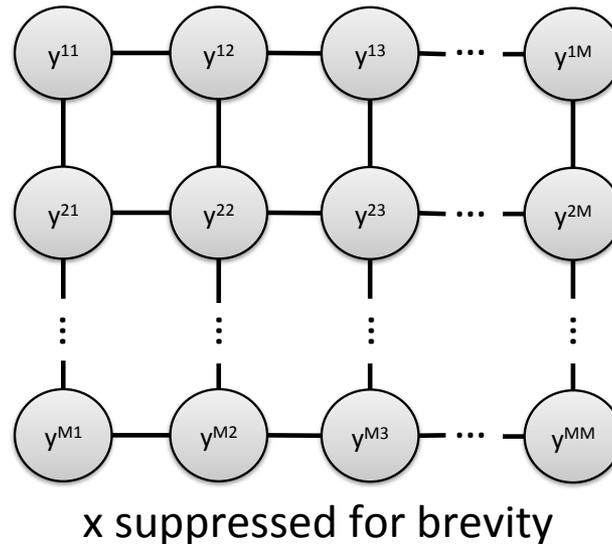
Loopy Graphical Models

Stereo (binocular)
Depth Detection



- Each y^{ij} is depth of pixel
- Neighbor pixels are similar
- Features over pairs of pixels
- “Loopy” Graphical Model
- Prediction is NP-Hard!

$$\operatorname{argmax}_y F(y, x)$$

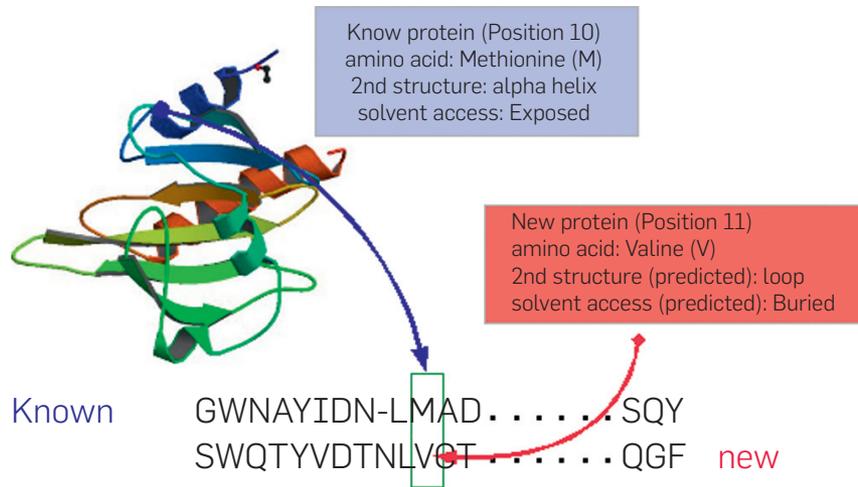


<http://vision.middlebury.edu/MRF/>

<http://www.seas.upenn.edu/~taskar/pubs/mmamn.pdf>

<http://www.cs.cornell.edu/~rdz/Papers/SZ-visalg99.pdf>

String Alignment



x = pair of strings (one from **D**)
 y = alignment

Predict Folding Structure
& Function of Protein

Database **D** of Known Proteins
(very well studied)

Larger Database **G** of Homologies
(proteins w/ known similarities to **D**)

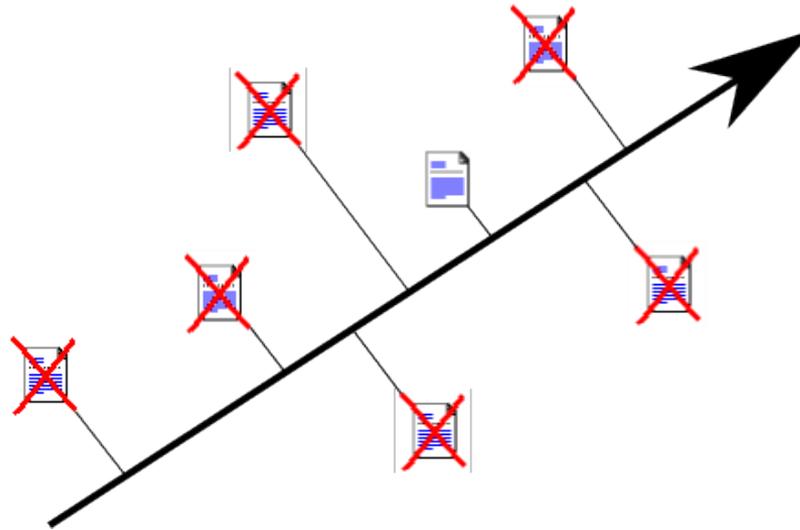
Train on **G**: learn how to align any
amino acid seq to proteins in **D**

$F(y, x)$ encodes score of different types
of substitutions, insertions & deletions

http://www.cs.cornell.edu/People/tj/publications/yu_etal_06a.pdf

See Also: <http://journals.plos.org/ploscompbiol/article?id=10.1371/journal.pcbi.1000173>

Ranking



Find w that predicts best ranking of search results.

Every relevant result should be above every non-relevant result.

$$y^{ij} \in \{-1, +1\}$$

$$F(y, x) = \sum_{i,j} y^{ij} [w^T \varphi(x^i) - w^T \varphi(x^j)]$$

x = query & set of results
 y = ranking

$$\operatorname{argmax}_y F(y, x) = \operatorname{sort} \left\{ w^T \varphi(x^j) \right\}_j$$

http://www.cs.cornell.edu/People/tj/publications/joachims_05a.pdf

http://research.microsoft.com/en-us/um/people/cburgess/tech_reports/MSR-TR-2010-82.pdf

http://www.yisongyue.com/publications/sigir2007_svmmap.pdf

Summary: Structured Prediction

- Very general setting
 - Applicable to prediction made jointly over multiple y 's
 - Prediction in Graphical Models
- Many learning algorithms for structured prediction
 - CRFs, SSVMs, Structured Perceptron, Learning Reductions
- Topic for Entire Class!

<http://www.nowozin.net/sebastian/cvpr2011tutorial/>

<http://www.cs.cmu.edu/~nasmith/sp4nlp/>

<http://www.cs.cornell.edu/Courses/cs778/2006fa/>

<https://www.sites.google.com/site/spflodd/>

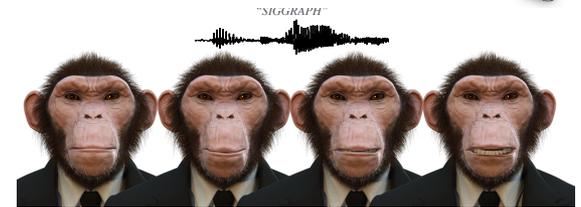
http://www.cs.cornell.edu/People/tj/publications/joachims_06b.pdf

Next Week

- **Lecture Tuesday:**
 - Learning Reductions
 - Recent Applications



- **NO Lecture Thursday:**
 - Student-Faculty Conference



- **Recitation Thursday:**
 - Review of Conditional Random Fields